# A New Parareal Algorithm for Problems with Discontinuous Sources I. Kulchytska<sup>1</sup>, M. J. Gander<sup>2</sup>, S. Schöps<sup>1</sup>, I. Niyonzima<sup>3</sup>

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TECHNISCHE

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# Outline of the Talk

#### Introduction

- Motivation
- The eddy current problem
- 2 Systems with highly-oscillatory excitations
  - Modified Parareal with reduced coarse dynamics
  - Convergence results for nonsmooth sources
  - Numerical example: induction machine
- 3 Acceleration of convergence to the steady state
  - Time-periodic eddy current problem
  - Parareal for time-periodic problems
  - Results for the induction machine
- 4 Conclusions and outlook

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# Motivation



- E-bike with a synchronous machine
- Robust geometry optimization
- Expensive time domain simulations



# Motivation



- E-bike with a synchronous machine
- Robust geometry optimization
- Expensive time domain simulations

![](_page_4_Picture_5.jpeg)

## The eddy current problem

Eddy current problem on domains  $\Omega_1$  and  $\Omega_2$ 

$$\boldsymbol{\sigma} \frac{\partial \vec{A}}{\partial t}(\vec{x},t) = -\nabla \times \left(\boldsymbol{\nu} \nabla \times \vec{A}(\vec{x},t)\right) + \vec{J}_{\rm s}(\vec{x},t)$$

with magnetic vector potential  $\vec{A}(\vec{x}, 0) = \vec{A}_0(\vec{x})$ , current density in coils and magnets  $\vec{J}_s$ , conductivity  $\sigma(\vec{x})$  and reluctivity  $\nu(\vec{x}, \vec{A})$ .

Spatial discretization yields initial value problem

$$\mathbf{Md}_t \mathbf{u}(t) = \mathbf{f}(t, \mathbf{u}(t)), \ t \in (0, T],$$
$$\mathbf{u}(0) = \mathbf{u}_0,$$

with unknown  $\mathbf{u}(t)$ , mass matrix  $\mathbf{M}$  and right-hand-side  $\mathbf{f}(...)$ .

![](_page_5_Picture_8.jpeg)

### The eddy current problem

Eddy current problem on domains Ω<sub>1</sub> and Ω<sub>2</sub>

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![](_page_7_Picture_8.jpeg)

# Challenges

![](_page_8_Figure_1.jpeg)

- Machines operate most of their life time in steady state
- Long simulation time until steady state is reached
- Effects on several time scales, e.g. due to pulsed excitations
- Many time steps yield time-consuming computation

# Challenges

![](_page_9_Figure_1.jpeg)

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parallel-in-time method

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# Parareal for highly-oscillatory discontinuous excitation

#### Parareal

- PWM (pulse width modulation): excitation contains high-order frequency components
- Propagators: fine *F* and coarse *G*
- Solver  $\mathcal{F}$  resolves high-frequency pulses
- Solver *G* might not capture dynamics

![](_page_11_Figure_6.jpeg)

PWM signal with a switching frequency of 500 Hz.

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### Idea

- Solve coarse problem for slowly-varying smooth input
- Low-frequency component: sinusoidal waveform  $\sin\left(\frac{2\pi}{T}t\right)$

![](_page_12_Figure_9.jpeg)

PWM signal with a switching frequency of 500 Hz and a sine wave of 50 Hz.

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### Question

What about convergence?

![](_page_13_Figure_11.jpeg)

PWM signal with a switching frequency of 500 Hz and a sine wave of 50 Hz.

Splitting of the nonsmooth excitation for  $t \in (0,T]$ 

 $\mathbf{M} \mathrm{d}_t \mathbf{u}(t) = \mathbf{f}(t, \mathbf{u}(t))$ 

Splitting of the nonsmooth excitation for  $t \in (0, T]$ 

$$\mathbf{M}d_t\mathbf{u}(t) = \mathbf{f}(t, \mathbf{u}(t)) = \overline{\mathbf{f}}(t, \mathbf{u}(t))$$

fast switching

slow smooth

Splitting of the nonsmooth excitation for  $t \in (0,T]$ 

$$\mathbf{M}\mathbf{d}_t\mathbf{u}(t) = \mathbf{f}(t, \mathbf{u}(t)) = \overline{\mathbf{f}}(t, \mathbf{u}(t))$$

slow smooth

![](_page_16_Picture_3.jpeg)

Reduced coarse propagator  $\overline{\mathcal{G}}$   $\mathbf{M} \mathbf{d}_t \mathbf{u}(t) = \overline{\mathbf{f}}(t, \mathbf{u}(t)),$  $\mathbf{u}(0) = \mathbf{u}_0$  • Original fine propagator  $\mathcal{F}$   $\mathbf{M} d_t \mathbf{u}(t) = \mathbf{f}(t, \mathbf{u}(t)),$  $\mathbf{u}(0) = \mathbf{u}_0$ 

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![](_page_17_Picture_3.jpeg)

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Modified Parareal update formula

 $\begin{aligned} \mathbf{U}_{0}^{(k+1)} &= \mathbf{u}_{0}, \\ \mathbf{U}_{n}^{(k+1)} &= \mathcal{F}(T_{n}, T_{n-1}, \mathbf{U}_{n-1}^{(k)}) + \bar{\mathcal{G}}(T_{n}, T_{n-1}, \mathbf{U}_{n-1}^{(k+1)}) - \bar{\mathcal{G}}(T_{n}, T_{n-1}, \mathbf{U}_{n-1}^{(k)}) \end{aligned}$ 

slow smooth

Splitting of the nonsmooth excitation for  $t \in (0,T]$ 

$$\mathbf{M}\mathbf{d}_t\mathbf{u}(t) = \mathbf{f}(t, \mathbf{u}(t)) = \overline{\mathbf{f}}(t, \mathbf{u}(t))$$

![](_page_18_Picture_3.jpeg)

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slow smooth

Proof: based on perturbation results for ODEs with discontinuities

#### **Theorem** (Gander, K.-R., Schöps, Niyonzima, '18)

• For  $\mathcal{I} := [0, T]$  let  $\Delta T = T/N$  denote window length and  $\mathcal{F}(T_n, T_{n-1}, \mathbf{U}_{n-1}^{(k)})$  be the exact solution to the original problem at  $T_n$ , with the RHS  $\mathbf{f} = \bar{\mathbf{f}} + \tilde{\mathbf{f}}$ . For  $p \ge 1$  we denote  $C_p = \|\tilde{\mathbf{f}}\|_{L^p(\mathcal{I},\mathbb{R}^n)}$  and let  $q \ge 1$  be given by 1/p + 1/q = 1.

• Assume  $\overline{\mathcal{G}}(T_n, T_{n-1}, \mathbf{U}_{n-1}^{(k)})$  is an approximation to the reduced problem with the smooth RHS  $\overline{\mathbf{f}}$ . The error is bounded by  $C_3 \Delta T^{l+1}$ , and let  $\overline{\mathcal{G}}$  satisfy the Lipschitz condition:

$$\|\bar{\mathcal{G}}(t+\Delta T,t,U) - \bar{\mathcal{G}}(t+\Delta T,t,Y)\| \le (1+C_2\Delta T)\|U-Y\|.$$

$$\bar{C}_1^k \left[ \bar{C}_4 C_p \Delta T^{(l+1)k+1/q} + \bar{C}_3 \left( \Delta T^{l+1} \right)^{k+1} \right] \frac{(1+C_2 \Delta T)^{n-k-1}}{(k+1)!} \prod_{j=0}^k (n-j).$$

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**RL-circuit model:** 

$$\frac{1}{R}\phi'(t) + \frac{1}{L}\phi(t) = f(t), \quad t \in (0,T],$$
  
$$\phi(0) = 0,$$

with  $R = 0.01 \ \Omega$ ,  $L = 0.001 \ \text{H}$ ,  $T = 0.02 \ \text{s}$ ; f- supplied PWM current source of  $20 \ \text{kHz}$ .

![](_page_23_Figure_4.jpeg)

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#### Choice of the coarse reduced input:

$$\bar{f}_{\text{step}}(t) = \begin{cases} 1, & t \in [0, T/2), \\ -1, & t \in [T/2, T) \end{cases}$$

![](_page_24_Figure_6.jpeg)

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![](_page_25_Figure_6.jpeg)

$$\bar{f}_{\mathbf{sine}}(t) = \sin\left(\frac{2\pi}{T}t\right), \ t \in [0,T]$$

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#### Choice of the coarse reduced input:

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$$\implies \tilde{f}(t) := f(t) - \bar{f}(t) \in \boldsymbol{L}^{\infty}(0, T) \iff 1/q = 1.$$

![](_page_26_Figure_7.jpeg)

![](_page_27_Figure_1.jpeg)

Convergence of the Parareal iteration k = 1 using the implicit Euler method (l = 1) and the reduced coarse step- and sine-input.

![](_page_28_Figure_1.jpeg)

Convergence of the Parareal iteration k = 2 using the implicit Euler method (l = 1) and the reduced coarse step- and sine-input.

![](_page_29_Figure_1.jpeg)

Convergence of the Parareal iteration k = 1 using the Crank-Nicolson scheme (l = 2) and the reduced coarse step- and sine-input.

# Application to an induction machine

![](_page_30_Figure_1.jpeg)

Four-pole squirrel cage 'im\_3kw' model and its magnetic field at t = 20 ms if excited by a sinusoidal voltage source (author: Gyselinck).

PWM voltage source of 5 kHz with a ramp-up and phase 1 of the corresponding sinusoidal waveform of 50 Hz.

# Numerical results

![](_page_31_Figure_1.jpeg)

voltage source of 20 kHz on [0, 20] ms. Software: implicit Euler within GetDP. Convergence of the standard Parareal and the modified Parareal algorithms to reach the prescribed tolerance  $1.5 \cdot 10^{-5}$ .

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- Time-periodic eddy current problem
- Parareal for time-periodic problems
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#### 4 Conclusions and outlook

# Time-periodic eddy current problem

Goal: obtain the steady-state solution

![](_page_33_Figure_2.jpeg)

Time / s

# Time-periodic eddy current problem

Goal: obtain the steady-state solution

![](_page_34_Figure_2.jpeg)

#### Time / s

Solve periodic boundary value problem in time:

 $\mathbf{M}d_t\mathbf{u}(t) = \mathbf{f}(t, \mathbf{u}(t)), \ t \in (0, T)$  with  $\mathbf{u}(0) = \mathbf{u}(T)$ .

# Parareal for time-periodic problems

![](_page_35_Figure_1.jpeg)

**PP-IC:** periodic parareal algorithm with initial value coarse problem:

$$\begin{split} \mathbf{U}_{0}^{(k+1)} &= \mathbf{U}_{N}^{(k)}, \\ \mathbf{U}_{n}^{(k+1)} &= \mathcal{F}(T_{n}, T_{n-1}, \mathbf{U}_{n-1}^{(k)}) + \mathcal{G}(T_{n}, T_{n-1}, \mathbf{U}_{n-1}^{(k+1)}) - \mathcal{G}(T_{n}, T_{n-1}, \mathbf{U}_{n-1}^{(k)}). \end{split}$$

M. J. Gander et al., *Analysis of Two Parareal Algorithms for Time-Periodic Problems*, SIAM Journal on Scientific Computing 35 (5), 2013.

# Results for induction machine with PWM voltage source

![](_page_36_Figure_1.jpeg)

Computational efforts to obtain the periodic (steady-state) solution:

- Sequential: 9 periods until the steady state ⇒ 2 176 179 system solves
- Parareal: calculation on [0,9T], needs effectively 583 707 linear solutions
- PP-IC: applied on one period [0, *T*], requires 194 038 linear solutions

Period T = 0.02 s, available CPUs N = 20

Fine propagator  $\mathcal{F}$ : three-phase PWM excitation of 20 kHz,  $\delta T = 10^{-6} \text{ s}$ Coarse solver  $\overline{\mathcal{G}}$ : three-phase sinusolidal source of 50 Hz,  $\Delta T = 10^{-3} \text{ s}$ 

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# **Conclusions and outlook**

#### Conclusions

- Introduced a new Parareal algorithm with reduced coarse dynamics
- Developed convergence theory for problems with (highly-oscillatory) discontinuous excitation
- Applied the modified Parareal method to the time-periodic eddy current problem for an induction machine model

# **Conclusions and outlook**

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### Outlook

- Prove convergence of the modified PP-IC algorithm
- Further development of parallel-in-time methods for the periodic eddy current problem with PWM excitation
- Combine the time-parallel techniques with spatial domain decomposition for simulation of electric machines

# Thank you!

#### ACKNOWLEDGEMENT

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![](_page_40_Picture_3.jpeg)

- M. J. Gander, I. Kulchytska-Ruchka, I. Niyonzima, and S. Schöps. *A new Parareal algorithm for problems with discontinuous sources*, 2018. Submitted, https://arxiv.org/abs/1803.05503.
- S. Schöps, I. Niyonzima, and M. Clemens, *Parallel-in-time simulation of eddy current problems using Parareal*, IEEE Trans. Magn. 54 (3), 2018.

J. Gyselinck, L. Vandevelde, and J. Melkebeek. *Multi-slice FE modeling of electrical machines with skewed slots-the skew discretization error*, IEEE Trans. Magn. 37(5), 2001.