

3. The fundamental group

3.1 Def.: a category C consists of:

(1) a class of objects, denoted $Ob(C)$ (or just C).

(2) for any pair $X, Y \in Ob(C)$, a set $C(X, Y)$, called the set of morphisms from X to Y ; $f \in C(X, Y)$ is usually denoted $X \xrightarrow{f} Y$.

(3) for any triple $X, Y, Z \in Ob(C)$, a "composition law" $C(Y, Z) \times C(X, Y) \xrightarrow{\circ} C(X, Z)$, $(g, f) \mapsto g \circ f$ (or gf)

such that:

(a) The composition is associative

(b) For any $X \in Ob(C)$, there exists an element $1_X \in C(X, X)$ neutral for the composition (left or right), called the identity of X .

3.2 Remark: If $Ob(C)$ is a set, we say that C is a small category.

3.3 Examples: (a) Set, the category with:

- $Ob(\text{Set})$: the class of sets.

- $\text{Set}(X, Y) =: \text{Map}(X, Y)$: the set of maps $X \rightarrow Y$

- $1_X: X \rightarrow X, x \mapsto x$; usual composition.

(b) Top, the category of topological spaces:

$Ob(\text{Top})$: the class of topological spaces.

$\text{Top}(X, Y) = \{ f \in \text{Set}(X, Y); f \text{ continuous} \}$

(c) Gp, the category of groups and group homomorphisms.

(d) Ring, the category of unital, associative rings and ring homomorphisms.

(e) R a ring; $R\text{-Mod}$ ($\text{Mod-}R$), the category ①

of left (right) R -modules.

Notice that none of the examples above are small.

The following are examples of small categories:

(f) If G is a group, define a category \underline{G} with a unique object $*$: $Ob(\underline{G}) = \{*\}$ and morphisms $\underline{G}(*, *) := G$ (underlying set of G), together with:

- $1_* = e$ (neutral element of G)

- Composition $\underline{G}(*, *) \times \underline{G}(*, *) \rightarrow \underline{G}(*, *)$ is the product of G : $g \circ f = gf$.

(g) \mathcal{Fin} , the category with objects

$$Ob(\mathcal{Fin}) = \{X \in \mathcal{P}(\mathbb{N}); \exists n, X = [n]\}$$

where $\underline{n} = \{a \in \mathbb{N}; 1 \leq a \leq n\}$

$\mathcal{Fin}(\underline{m}, \underline{n}) = \text{Set}(\underline{m}, \underline{n})$, and usual composition.

(h) We can also take smaller sets of morphisms:

$$\mathcal{I}: Ob(\mathcal{I}) = Ob(\mathcal{Fin})$$

$$\mathcal{I}(\underline{m}, \underline{n}) = \{\alpha \in \mathcal{Fin}(\underline{m}, \underline{n}); \alpha \text{ injective}\}$$

$$\Sigma: Ob(\Sigma) = Ob(\mathcal{Fin})$$

$$\Sigma(\underline{m}, \underline{n}) = \{\alpha \in \mathcal{Fin}(\underline{m}, \underline{n}); \alpha \text{ bijective}\}$$

3.4 Definition: let C be a category. A morphism $f \in C(X, Y)$ is called an isomorphism if $\exists g \in C(Y, X)$, $f \circ g = id_Y$ & $g \circ f = id_X$ (then unique! Noted f^{-1})
A groupoid is a small category C where all morphisms are isomorphisms.

3.5 Examples: In 3.3, \underline{G} and Σ are groupoids.

3.6 Definition: let C be a category. We define the

opposite category C^{op} by: $Ob(C^{op}) = Ob(C)$, and for any $x, y \in Ob(C^{op})$,

$$C^{op}(x, y) := C(y, x), \text{ together with}$$

$$C^{op}(y, z) \times C^{op}(x, y) \rightarrow C(x, z)$$

$$(f^{op}, g^{op}) \mapsto f^{op} \circ g^{op} := (g \circ f)^{op}$$

↑ in C .

"Reverse all arrows".

3.7 Definition let C, D be categories. A functor

$F: C \rightarrow D$ is

- (a) A relation assigning to each $x \in Ob(C)$ a unique $F(x) \in Ob(D)$.
- (b) For all $x, y \in Ob(C)$, $F = F_{x,y}: C(x, y) \rightarrow D(F(x), F(y))$ such that $F(1_x) = 1_{F(x)}$, for all $x \in Ob(C)$, and $F(g) \circ F(f) = F(g \circ f)$ for all composable pair (g, f) of morphisms in C .

A cofunctor or a contravariant functor $C \rightarrow D$ is a functor $C^{op} \rightarrow D$ (spell it out!).

3.8 Examples: (a) If C, D are categories, and $z \in Ob(D)$, define the constant functor $c_z: C \rightarrow D$ by $c_z(x) = z$ for all $x \in Ob(C)$, and $c_z(f) = 1_z$ for all morphisms of C .

(b) We have the forgetful functors

$F: Top \rightarrow Sets$, $F: Grp \rightarrow Sets$, $F: R\text{-Mod} \rightarrow Sets$:
 $F(x) =$ underlying set of x , $F(f) =$ underlying map of sets.

(c) If C is a category and $x \in Ob(C)$, we have a cofunctor $F^x: C \rightarrow Sets$, given by

$F^x(y) = C(y, x)$ for all $y \in Ob(C)$, and for $f: y \rightarrow z$ in C , $F^x(f): C(z, x) \rightarrow C(y, x)$, $g \mapsto g \circ f$. ③

It is called the co-functor represented by X .

Similarly, we have a functor $F_X : C \rightarrow \text{Sets}$

called the functor co-represented by $X : F_X(Y) = C(X, Y)$,

and $F_X(f) : C(X, Y) \rightarrow C(X, Z)$ for any $f: Y \rightarrow Z$ in C .
 $\alpha \mapsto f \circ \alpha$

(d) If C is a category, we have the identity functor

$\text{Id}_C : C \rightarrow C$, $\text{Id}_C(X) = X$ and $\text{Id}_C(f) = f$.

3.9 Definition : let C be a category. A sub-category of C is a category D with

(i) $\text{Ob}(D) \subset \text{Ob}(C)$

(ii) $\forall X, Y \in \text{Ob}(D)$, $D(X, Y) \subset C(X, Y)$

(iii) The inclusion $D \rightarrow C$ is a functor.

We say that D is a full subcategory of C if for any $X, Y \in \text{Ob}(D)$, $D(X, Y) = C(X, Y)$.

3.10 Examples : (a) Fin is a full subcategory of Set
 Σ is a (non full) subcategory of \mathbb{I} , which is a (non-full) subcategory of Fin .

(b) Gr is not a subcategory of Set !

Top is not a subcategory of Set !

(c) Ab , the full subcategory of Gr , consisting of abelian groups.

(d) If D is a subcategory of C , we have a functor

$i : D \rightarrow C$, $i(X) = X$, $i(f) = f$, by defini-

tion of a subcategory.

3.11 Definition: If $C \xrightarrow{F} D$ and $D \xrightarrow{G} E$ are functors, we can define the composition functor $G \circ F: C \rightarrow E$ by $(G \circ F)(x) = G(F(x))$ for any $x \in \text{Ob}(C)$, and $(G \circ F)(f) = G(F(f))$ for any $f: X \rightarrow Y$ in C .

3.12 Remark: The composition of functors is associative, and identity functors are neutral for the composition.

3.13 Exercise: We have defined the notion of a product, coproduct, pull-back, push-out of spaces by solely using the notion of a category. Can do the same for any category (but they do not nec. exist!).

▷ We will introduce more categorical notions when needed!

We now introduce the homotopy category of spaces

As above (and as in chapter 1), we denote by Top the category of topological spaces and continuous maps.

3.14 Def For $f, g \in \text{Top}(X, Y)$, a homotopy from f to g

is a map $H: X \times I \rightarrow Y$, $I = [0, 1] \subset \mathbb{R}$, such that

$$\begin{array}{ccccc} X & \xrightarrow{i_0} & X \times I & \xleftarrow{i_1} & X \\ & \searrow f & \downarrow H & \swarrow g & \\ & & Y & & \end{array} \text{ commutes; here } i_t: X \rightarrow X \times I$$

$x \mapsto (x, t)$

We denote this by $f \stackrel{H}{\simeq} g$. We say that f and g are

homotopic (denoted $f \simeq g$) if $\exists H, f \stackrel{H}{\simeq} g$.

We denote $H_t := H \circ i_t: X \rightarrow Y$.

3.15 Lemma: The relation \simeq on $\text{Top}(X, Y)$ is an equivalence rel.

This relation is compatible with composition in the sense that

$$\begin{array}{ccc} \text{Top}(Y, Z) \times \text{Top}(X, Y) & \xrightarrow{\circ} & \text{Top}(X, Z) \\ \downarrow & & \downarrow \\ g \circ g' & & f \circ f' \end{array} \quad \begin{array}{l} f \simeq f' \text{ and } g \simeq g' \\ \Rightarrow g \circ f \simeq g' \circ f'. \quad \textcircled{5} \end{array}$$

proof: let $f, g, h \in \text{Top}(X, Y)$.

By $X \times I \xrightarrow{H} Y$, $H(x, t) = f(x) \forall (x, t)$, we see $f \stackrel{H}{\simeq} f$.

If $f \stackrel{K}{\simeq} g$, then $g \stackrel{L}{\simeq} f$ by $L: X \times I \rightarrow Y$, $L(x, t) = K(x, 1-t)$

If $f \stackrel{K}{\simeq} g \stackrel{L}{\simeq} h$, then $f \stackrel{K*L}{\simeq} h$ where $K*L: X \times I \rightarrow Y$ is

$$\text{given by } K*L(x, t) = \begin{cases} K(x, 2t) & \text{if } 0 \leq t \leq \frac{1}{2} \\ L(x, 2t-1) & \text{if } \frac{1}{2} \leq t \leq 1. \end{cases}$$

Thus \simeq is an equivalence relation on $\text{Top}(X, Y)$.

For the compatibility with composition, given $f \stackrel{F}{\simeq} f'$ and $g \stackrel{G}{\simeq} g'$, we use transitivity $g \circ f \stackrel{K}{\simeq} g' \circ f \stackrel{L}{\simeq} g' \circ f'$ for

$$K: X \times I \xrightarrow{f' \times \text{id}} Y \times I \xrightarrow{G} Z, \quad L: X \times I \xrightarrow{F} Y \xrightarrow{g'} Z. \quad \square$$

3.16 Def We define $h\text{Top}$, the homotopy category of spaces by $\text{Ob}(h\text{Top}) = \text{Ob}(\text{Top})$, $h\text{Top}(X, X) := [X, X] := \text{Top}(X, X) / \simeq$.

The class of $f \in \text{Top}(X, Y)$ in $[X, Y]$ is denoted $[f]$, and

composition is defined by $[f] \circ [g] := [f \circ g]$ (well defined by 3.15). The identity of $X \in h\text{Top}$ is $1_X = [\text{id}_X]$

Remark: We have an obvious functor $\text{Top} \rightarrow h\text{Top}$.

3.17 Def: A map $f: X \rightarrow Y$ is called a homotopy equivalence if $[f] \in h\text{Top}(X, Y)$ is an isomorphism.

We say that spaces X, Y are homotopy equivalent, (denoted $X \simeq Y$), if they are isomorphic in $h\text{Top}$. We say that X is contractible if $X \simeq \{*\}$ (one-point space).

3.18 Examples (a) Given X a space, any $f, g: X \rightarrow \mathbb{R}^n$ ($n \in \mathbb{N}$)

are homotopic: $f \stackrel{H}{\simeq} g$ with $H: X \times I \rightarrow \mathbb{R}^n$, $H(x, t) = (1-t)f(x) + t g(x)$.

Thus $[X, \mathbb{R}^n]$ has a unique element!

In particular, $\{0\} \hookrightarrow \mathbb{R}^n$ is a homotopy equivalence, thus \mathbb{R}^n is contractible. (6)

(b) Suppose $f: X \rightarrow S^u$ is non surjective. Then f is homotopic to a constant map.

Proof: Assume $\text{Im}(f) \subset S^u \setminus \{N\}$.

We have a homeomorphism $\mathbb{R}^u \xrightarrow{h} S^u \setminus \{N\}$, $0 \mapsto S$

Therefore f factorises as $X \xrightarrow{g} \mathbb{R}^u \xrightarrow{h} S^u \setminus \{N\}$.

If $c_0: X \rightarrow \mathbb{R}^u$ is the constant map to $0 \in \mathbb{R}^u$, we know by (a) that $\exists H: X \times I \rightarrow \mathbb{R}^u$, $g \stackrel{h}{\simeq} c_0$.

Thus by Lemma 3.15, $ihH: X \times I \rightarrow S^u \setminus \{N\} \xrightarrow{i} S^u$ is a homotopy between f and c_s .

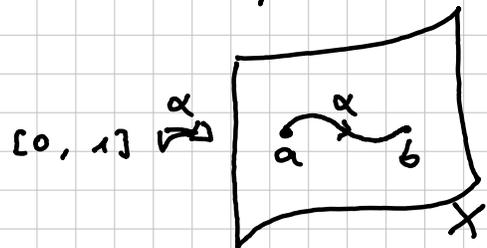
(c) The inclusion $S^u \hookrightarrow \mathbb{R}^{u+1} \setminus \{0\}$ is a homotopy equivalence (exercise).

(d) $[S^u, S^m]$ is very hard to study!

3.19 Definition: let X be a space, and $a, b \in X$.

A path from a to b in X is a continuous map $\alpha: I \rightarrow X$ with $\alpha(0) = a$ and $\alpha(1) = b$.

Denote by $\Omega(X, a, b)$ the set of all paths from a to b in X .



We say that $\alpha, \beta \in \Omega(X, a, b)$ are homotopic relative to $\partial I = \{0, 1\}$ if $\exists H: I \times I \rightarrow X$, s.t.

(i) $H_0(s) := H(s, 0) = \alpha(s)$ and $H_1(s) = H(s, 1) = \beta(s)$ for all $s \in I$;

(ii) $H_t(0) = H(0, t) = a$ and $H_t(1) = H(1, t) = b$ for all $t \in I$.

We denote it by $\alpha \sim \beta$ or $\alpha \stackrel{H}{\sim} \beta$.

3.20 Lemma \sim is an equivalence relation on $\Omega(X, a, b)$. $\textcircled{7}$