

$\texttt{FC-VFEMP}_1\text{-}\texttt{BIHARMONIC}$ Python package, User's Guide 1

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Abstract

FC-VFEMP₁-BIHARMONIC is an **experimental** object-oriented Python package dedicated to solve **bi-harmonic** boundary value problems (BVP) by using \mathbb{P}^1 -Lagrange finite element method in any space dimension. This package is an add-on to the FC-VFEMP₁ package [?]. It uses the FC-SIMESH package [1] and the **siMesh** class which allows to use simplices meshes generated from gmsh (in dimension 2 or 3) or an hypercube triangulation (in any dimension).

The two FC-SIMESH add-ons FC-SIMESH-MATPLOTLIB [2] and FC-SIMESH-MAYAVI [3] allows a great flexibility in graphical representations of the meshes and datas on the meshes by using respectively the MATPLOTLIB and the MAYAVI packages.

The FC-VFEMP₁ package also contains the techniques of vectorization presented in [5] and extended in [4] and allows good performances when using \mathbb{P}^1 -Lagrange finite element method.

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Chapter 1

Generic Boundary Value Problems

The notations of [8] are employed in this section and extended to the vector case.

1.1 Scalar boundary value problem

Let Ω be a bounded open subset of \mathbb{R}^d , $d \ge 1$. The boundary of Ω is denoted by Γ .

We denote by $\mathcal{L}_{\mathbb{A},\boldsymbol{b},\boldsymbol{c},a_0} = \mathcal{L} : \mathrm{H}^2(\Omega) \longrightarrow L^2(\Omega)$ the second order linear differential operator acting on scalar fields defined, $\forall u \in \mathrm{H}^2(\Omega)$, by

$$\mathcal{L}_{\mathbb{A},\boldsymbol{b},\boldsymbol{c},a_0}(u) \stackrel{\text{def}}{=} -\operatorname{div}\left(\mathbb{A}\,\boldsymbol{\nabla}\,u\right) + \operatorname{div}\left(\boldsymbol{b}u\right) + \langle\boldsymbol{\nabla}\,u,\boldsymbol{c}\rangle + a_0u \tag{1.1}$$

where $\mathbb{A} \in (L^{\infty}(\Omega))^{d \times d}$, $\mathbf{b} \in (L^{\infty}(\Omega))^d$, $\mathbf{c} \in (L^{\infty}(\Omega))^d$ and $a_0 \in L^{\infty}(\Omega)$ are given functions and $\langle \cdot, \cdot \rangle$ is the usual scalar product in \mathbb{R}^d . We use the same notations as in the chapter 6 of [8] and we note that we can omit either div $(\mathbf{b}u)$ or $\langle \nabla u, \mathbf{c} \rangle$ if \mathbf{b} and \mathbf{c} are sufficiently regular functions. We keep both terms with \mathbf{b} and \mathbf{c} to deal with more boundary conditions. It should be also noted that it is important to preserve the two terms \mathbf{b} and \mathbf{c} in the generic formulation to enable a greater flexibility in the choice of the boundary conditions.

Let Γ^D , Γ^R be open subsets of Γ , possibly empty and $f \in L^2(\Omega)$, $g^D \in \mathrm{H}^{1/2}(\Gamma^D)$, $g^R \in L^2(\Gamma^R)$, $a^R \in L^{\infty}(\Gamma^R)$ be given data.

A scalar boundary value problem is given by

Scalar BVP 1 : generic problem Find $u \in H^{2}(\Omega)$ such that $\mathcal{L}(u) = f$ in Ω , (1.2) $u = g^{D}$ on Γ^{D} , (1.3)

$$\frac{\partial u}{\partial n_{\mathcal{L}}} + a^R u = g^R \qquad \qquad \text{on } \Gamma^R. \tag{1.4}$$

The **conormal derivative** of u is defined by

$$\frac{\partial u}{\partial n_{\mathcal{L}}} \stackrel{\text{def}}{=} \langle \mathbb{A} \, \boldsymbol{\nabla} \, u, \boldsymbol{n} \rangle - \langle \boldsymbol{b} u, \boldsymbol{n} \rangle \tag{1.5}$$

The boundary conditions (1.3) and (1.4) are respectively **Dirichlet** and **Robin** boundary conditions. Neumann boundary conditions are particular Robin boundary conditions with $a^R \equiv 0$. To have an outline of the FC-VFEMP $_1$ package, a first and simple problem is quickly present. Explanations will be given in next sections.

The problem to solve is the Laplace problem for a condenser.

-`(<i>Usual</i> BVP 1 : 2D condenser problem	
	Find $u \in \mathrm{H}^2(\Omega)$ such that	
	$-\Delta u = 0 \text{ in } \Omega \subset \mathbb{R}^2,$	(1.6)
	$u = 0 \text{ on } \Gamma_1,$	(1.7)
	$u = -12 \text{ on } \Gamma_{98},$	(1.8)
	$u = 12$ on Γ_{99} ,	(1.9)

where Ω and its boundaries are given in Figure 1.1.



Figure 1.1: 2D condenser mesh and boundaries (left) and numerical solution (right)

The problem (1.6)-(1.9) can be equivalently expressed as the scalar BVP (1.2)-(1.4):

Scalar BVP 2 : 2D condenser problem
Find
$$u \in H^2(\Omega)$$
 such that
 $\mathcal{L}(u) = f$ in Ω ,
 $u = g^D$ on $\Gamma^D = \Gamma_1 \cup \Gamma_{98} \cup \Gamma_{99}$.
where $\mathcal{L} := \mathcal{L}_{\mathbb{I},\mathbf{0},\mathbf{0},0}, f \equiv 0$, and
 $g^D := 0$ on $\Gamma_1, g^D := -12$ on $\Gamma_{98}, g^D := +12$ on Γ_{99}

In Listing 27 a complete code is given to solve this problem.

```
meshfile=gmsh.buildmesh2d('condenser',10) # generate mesh
Th=siMesh(meshfile) # read mesh
Lop=Loperator(dim=2, d=2, A=[[1, 0], [0, 1]])
pde=PDE(Op=Lop)
bvp=BVP(Th, pde=pde)
bvp.setDirichlet(1, 0.)
bvp.setDirichlet (98, -12.)
bvp.setDirichlet(-99,+12.)
u=bvp.solve();
\# Graphic parts
plt.figure(1)
siplt.plotmesh(Th, legend=True)
set_axes_equal()
plt.figure(2)
siplt.plotmesh(Th, color='LightGray', alpha=0.3)
siplt.plotmesh(Th,d=1,legend=True)
```

```
set_axes_equal()
plt.figure(3)
siplt.plot(Th,u)
plt.colorbar(label='u')
set_axes_equal()
plt.figure(4)
siplt.plotiso(Th,u,contours=15)
plt.colorbar(label='u')
siplt.plotmesh(Th,color='LightGray',alpha=0.3)
plt.axis('off');set_axes_equal()
```

Listing 1.1: Complete Python code to solve the 2D condenser problem with graphical representations



Figure 1.2: 2D condenser numerical solution

Vector boundary value problem

Let $m \ge 1$ and \mathcal{H} be the *m*-by-*m* matrix of second order linear differential operators defined by

$$\begin{cases} \mathcal{H} : (\mathrm{H}^{2}(\Omega))^{m} \longrightarrow (L^{2}(\Omega))^{m} \\ \boldsymbol{u} = (\boldsymbol{u}_{1}, \dots, \boldsymbol{u}_{m}) \longmapsto \boldsymbol{f} = (\boldsymbol{f}_{1}, \dots, \boldsymbol{f}_{m}) \stackrel{\mathsf{def}}{=} \mathcal{H}(\boldsymbol{u}) \end{cases}$$
(1.10)

where

$$\boldsymbol{f}_{\alpha} = \sum_{\beta=1}^{m} \mathcal{H}_{\alpha,\beta}(\boldsymbol{u}_{\beta}), \quad \forall \alpha \in [\![1,m]\!],$$
(1.11)

with, for all $(\alpha, \beta) \in [\![1, m]\!]^2$,

1.2

$$\mathcal{H}_{\alpha,\beta} \stackrel{\mathsf{def}}{=} \mathcal{L}_{\mathbb{A}^{\alpha,\beta},\boldsymbol{b}^{\alpha,\beta},\boldsymbol{c}^{\alpha,\beta},\boldsymbol{a}_{0}^{\alpha,\beta}} \tag{1.12}$$

and $\mathbb{A}^{\alpha,\beta} \in (L^{\infty}(\Omega))^{d \times d}$, $\boldsymbol{b}^{\alpha,\beta} \in (L^{\infty}(\Omega))^d$, $\boldsymbol{c}^{\alpha,\beta} \in (L^{\infty}(\Omega))^d$ and $a_0^{\alpha,\beta} \in L^{\infty}(\Omega)$ are given functions. We can also write in matrix form

$$\mathcal{H}(\boldsymbol{u}) = \begin{pmatrix} \mathcal{L}_{\mathbb{A}^{1,1},\boldsymbol{b}^{1,1},\boldsymbol{c}^{1,1},a_0^{1,1}} & \cdots & \mathcal{L}_{\mathbb{A}^{1,m},\boldsymbol{b}^{1,m},\boldsymbol{c}^{1,m},a_0^{1,m}} \\ \vdots & \ddots & \vdots \\ \mathcal{L}_{\mathbb{A}^{m,1},\boldsymbol{b}^{m,1},\boldsymbol{c}^{m,1},a_0^{m,1}} & \cdots & \mathcal{L}_{\mathbb{A}^{m,m},\boldsymbol{b}^{m,m},\boldsymbol{c}^{m,m},a_0^{m,m}} \end{pmatrix} \begin{pmatrix} \boldsymbol{u}_1 \\ \vdots \\ \boldsymbol{u}_m \end{pmatrix}.$$
(1.13)

We remark that the \mathcal{H} operator for m = 1 is equivalent to the \mathcal{L} operator.

For $\alpha \in [\![1,m]\!]$, we define Γ^D_{α} and Γ^R_{α} as open subsets of Γ , possibly empty, such that $\Gamma^D_{\alpha} \cap \Gamma^R_{\alpha} = \emptyset$. Let $\mathbf{f} \in (L^2(\Omega))^m$, $g^D_{\alpha} \in \mathrm{H}^{1/2}(\Gamma^D_{\alpha})$, $g^R_{\alpha} \in L^2(\Gamma^R_{\alpha})$, $a^R_{\alpha} \in L^{\infty}(\Gamma^R_{\alpha})$ be given data.

A vector boundary value problem is given by

Vector BVP 1 : generic problem

Find $\boldsymbol{u} = (\boldsymbol{u}_1, \dots, \boldsymbol{u}_m) \in (\mathrm{H}^2(\Omega))^m$ such that

$$\mathcal{H}(\boldsymbol{u}) = \boldsymbol{f} \qquad \qquad \text{in } \Omega, \qquad (1.14)$$

on
$$\Gamma^D_{\alpha}, \ \forall \alpha \in [\![1,m]\!],$$
 (1.15)

$$\frac{\partial \boldsymbol{u}}{\partial n_{\mathcal{H}_{\alpha}}} + a_{\alpha}^{R} \boldsymbol{u}_{\alpha} = g_{\alpha}^{R} \qquad \text{on } \Gamma_{\alpha}^{R}, \ \forall \alpha \in [\![1,m]\!], \qquad (1.16)$$

where the α -th component of the **conormal derivative** of **u** is defined by

 $\boldsymbol{u}_{\alpha} = g_{\alpha}^{D}$

$$\frac{\partial \boldsymbol{u}}{\partial n_{\mathcal{H}_{\alpha}}} \stackrel{\text{def}}{=} \sum_{\beta=1}^{m} \frac{\partial \boldsymbol{u}_{\beta}}{\partial n_{\mathcal{H}_{\alpha,\beta}}} = \sum_{\beta=1}^{m} \left(\left\langle \mathbb{A}^{\alpha,\beta} \, \boldsymbol{\nabla} \, \boldsymbol{u}_{\beta}, \boldsymbol{n} \right\rangle - \left\langle \boldsymbol{b}^{\alpha,\beta} \, \boldsymbol{u}_{\beta}, \boldsymbol{n} \right\rangle \right). \tag{1.17}$$

The boundary conditions (1.16) are the **Robin** boundary conditions and (1.15) is the **Dirichlet** boundary condition. The **Neumann** boundary conditions are particular Robin boundary conditions with $a_{\alpha}^{R} \equiv 0$.

In this problem, we may consider on a given boundary some conditions which can vary depending on the component. For example we may have a Robin boundary condition satisfying $\frac{\partial \boldsymbol{u}}{\partial n_{\mathcal{H}_1}} + a_1^R \boldsymbol{u}_1 = g_1^R$ and a Dirichlet one with $\boldsymbol{u}_2 = g_2^D$.

To have an outline of the FC-VFEM \mathbb{P}_1 package, a second and simple problem is quickly present.

 $\begin{array}{c|c} & \overleftarrow{\bullet} & Usual \text{ vector BVP 1}: 2D \text{ simple vector problem} \\ & \text{Find } \mathbf{u} = (u_1, u_2) \in (\mathrm{H}^2(\Omega))^2 \text{ such that} \\ & & -\Delta u_1 + u_2 = 0 \text{ in } \Omega \subset \mathbb{R}^2, \\ & & -\Delta u_2 + u_1 = 0 \text{ in } \Omega \subset \mathbb{R}^2, \\ & & (1.18) \\ & & -\Delta u_2 + u_1 = 0 \text{ in } \Omega \subset \mathbb{R}^2, \\ & & (1.19) \\ & & (u_1, u_2) = (0, 0) \text{ on } \Gamma_1, \\ & & (u_1, u_2) = (-12, +12.) \text{ on } \Gamma_{98}, \\ & & (1.21) \\ & & (u_1, u_2) = (+12, -12.) \text{ on } \Gamma_{99}, \end{array}$

where Ω and its boundaries are given in Figure 1.1. The problem (1.18)-(1.22) can be equivalently expressed as the vector BVP (1.2)-(1.4) :

Find $\mathbf{u} = (u_1, u_2) \in (\mathrm{H}^2(\Omega))^2$ such that $\mathcal{H}(\mathbf{u}) = \mathbf{f} \qquad \qquad \text{in } \Omega, \\
u_1 = g_1^D \qquad \qquad \text{on } \Gamma^D = \Gamma_1 \cup \Gamma_{98} \cup \Gamma_{99}, \\
u_2 = g_2^D \qquad \qquad \text{on } \Gamma^D = \Gamma_1 \cup \Gamma_{98} \cup \Gamma_{99}, \\
\text{where} \qquad \qquad \mathcal{H} := \begin{pmatrix} \mathcal{L}_{\mathbb{I}}, \mathbf{o}, \mathbf{o}, 0 & \mathcal{L}_{\mathbb{O}}, \mathbf{o}, \mathbf{o}, 1 \\ \mathcal{L}_{\mathbb{O}}, \mathbf{o}, 0, 1 & \mathcal{L}_{\mathbb{H}}, \mathbf{o}, \mathbf{o}, 0 \end{pmatrix}, \text{ as } \mathcal{H} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} -\Delta & 1 \\ 1 & -\Delta \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} \\
f \equiv 0, \\
\text{and} \\
g_1^D = g_2^D := 0 \text{ on } \Gamma_1, \ g_1^D := -12, \ g_2^D := +12 \text{ on } \Gamma_{98}, \ g_1^D := +12, \ g_2^D := -12 \text{ on } \Gamma_{99} \end{cases}$

In Listing 21 a complete code is given to solve this problem. Numerical solutions are given in Figure 1.3.

meshfile=gmsh.buildmesh2d('condenser',10); # generate mesh Th=siMesh(meshfile) # read mesh Hop1=Loperator(dim=2,A=[[1,None],[None,1]])

```
Hop2=Loperator(dim=2,a0=1)
\texttt{Hop}=\texttt{Hoperator}(\texttt{dim}=2,\texttt{m}=2,\texttt{H}=[[\texttt{Hop1},\texttt{Hop2}],[\texttt{Hop2},\texttt{Hop1}]])
pde=PDE(Op=Hop)
bvp=BVP(Th, pde=pde)
bvp.setDirichlet (1, 0, comps = [0, 1])
bvp.setDirichlet ( 98, [-12, +12], comps = [0, 1]);
bvp.setDirichlet (99, [+12, -12], comps = [0, 1]);
U=bvp.solve(split=True)
\# Graphic parts
plt.figure(1)
siplt.plot(Th,U[0])
plt.axis('off');set_axes_equal()
plt.colorbar(label='u_1', orientation='horizontal')
plt.figure(2)
siplt.plot(Th,U[1])
plt . axis ('off'); set_axes_equal()
plt . colorbar (label='$u_2$', orientation='horizontal')
```

Listing 1.2: Complete Python code to solve the funny 2D vector problem with graphical representations



Figure 1.3: Funny vector BVP, u_1 numerical solution (left) and u_2 numerical solution (right)

Chapter 2

Biharmonic Boundary Value Problems

Let $\Omega \subset \mathbb{R}^{\dim}$ and $\Gamma = \partial \Omega$. The biharmonic equation is the fourth-order partial PDE given by

$$\Delta^2 u = f, \quad \text{in } \Omega \tag{2.1}$$

where $\Delta^2 u = \Delta(\Delta u) = \sum_{i=1}^{\dim} \sum_{j=1}^{\dim} \frac{\partial^4 u}{\partial x_i^2 \partial x_j^2} = \sum_{i=1}^{\dim} \frac{\partial^4 u}{\partial x_i^4} + 2 \sum_{i=1}^{\dim} \sum_{j=i+1}^{\dim} \frac{\partial^4 u}{\partial x_i^2 \partial x_j^2}$ The boundary conditions on Γ can be

• Clamped Plate (CP) or pure Dirichlet type:

$$u = \frac{\partial u}{\partial \boldsymbol{n}} = g \tag{2.2}$$

• Simply Supported Plate (SSP) or Navier type :

$$u = \Delta u = g \tag{2.3}$$

• Pure Hinged Plate (PHP) or Steklov type :

$$u = \Delta u - (1 - \sigma) K \frac{\partial u}{\partial \boldsymbol{n}} = g$$
(2.4)

• Cahn-Hilliard (CH) type

$$\frac{\partial u}{\partial n} = \frac{\partial \Delta u}{\partial n} = g \tag{2.5}$$

2.1

Link with $\mathcal H$ -operator

Classically the fourth-order PDE (2.1) is converted to the two second-order PDE

$$-\Delta u = v \tag{2.6}$$

$$-\Delta v = f \tag{2.7}$$

These two equations can be equivalently written as

$$\mathcal{G}\begin{pmatrix} u\\v \end{pmatrix} = \begin{pmatrix} f\\0 \end{pmatrix} \quad \text{or} \quad \mathcal{K}\begin{pmatrix} u\\v \end{pmatrix} = \begin{pmatrix} 0\\f \end{pmatrix}$$
 (2.8)

where \mathcal{G} and \mathcal{K} are the \mathcal{H} -operators defined by

$$\mathcal{G} = \begin{pmatrix} 0 & \mathcal{L}_{\mathbb{I},\mathbf{0},\mathbf{0},0} \\ \mathcal{L}_{\mathbb{I},\mathbf{0},\mathbf{0},0} & \mathcal{L}_{\mathbb{O},\mathbf{0},\mathbf{0},-1} \end{pmatrix} \text{ and } \mathcal{K} = \begin{pmatrix} \mathcal{L}_{\mathbb{I},\mathbf{0},\mathbf{0},0} & \mathcal{L}_{\mathbb{O},\mathbf{0},\mathbf{0},-1} \\ \mathcal{L}_{\mathbb{O},\mathbf{0},\mathbf{0},0} & \mathcal{L}_{\mathbb{I},\mathbf{0},\mathbf{0},0} \end{pmatrix}$$
(2.9)

The Python code using the FC-VFEMP₁ package to create the operators \mathcal{G} and \mathcal{K} are respectively given in Listings 2.1 and 2.2.

<pre>from fc_vfemp1.operators import</pre>	<pre>from fc_vfemp1.operators import</pre>
Loperator , Hoperator	Loperator , Hoperator
Lop=Loperator(dim=2,	Lop=Loperator(dim=2,
A = [[1, None], [None, 1]])	A = [[1, None], [None, 1]])
Gop=Hoperator(dim=2,m=2)	Kop=Hoperator(dim=2,m=2)
Gop.H[0][1] = Gop.H[1][0] = Lop	Kop . H[0][0] = Kop . H[1][1] = Lop
Gop.H[1][1] = Loperator(dim=2, a0=-1)	Kop.H[0][1] = Loperator $(dim=2, a0=-1)$
Listing 2.1: \mathcal{G} operator with the FC-VFEMP ₁	Listing 2.2: \mathcal{K} operator with the FC-VFEM \mathbb{P}_1

Listing 2.1: \mathcal{G} operator with the FC-VFEMP₁ Listing packagein 2D package

Listing 2.2: \mathcal{K} operator with the FC-VFEM \mathbb{P}_1 package in 2D

Let $\boldsymbol{w} = (u, v)$. With the operator \mathcal{K} given in (2.8), the components of the conormal derivative of \boldsymbol{w} defined in (1.17) are given by

$$\frac{\partial \boldsymbol{w}}{\partial n_{\mathcal{K}_{1}}} \stackrel{\text{def}}{=} \sum_{\beta=1}^{2} \frac{\partial \boldsymbol{w}_{\beta}}{\partial n_{\mathcal{K}_{1,\beta}}} = \sum_{\beta=1}^{2} \left\langle \mathbb{A}^{1,\beta} \, \boldsymbol{\nabla} \, \boldsymbol{w}_{\beta}, \boldsymbol{n} \right\rangle - \left\langle \boldsymbol{b}^{1,\beta} \boldsymbol{u}_{\beta}, \boldsymbol{n} \right\rangle \\
= \left\langle \mathbb{I} \, \boldsymbol{\nabla} \, \boldsymbol{w}_{1}, \boldsymbol{n} \right\rangle = \left\langle \boldsymbol{\nabla} \, \boldsymbol{u}, \boldsymbol{n} \right\rangle \\
= \frac{\partial u}{\partial \boldsymbol{n}}$$
(2.10)

 and

$$\frac{\partial \boldsymbol{w}}{\partial n_{\mathcal{K}_{2}}} \stackrel{\text{def}}{=} \sum_{\beta=1}^{2} \frac{\partial \boldsymbol{w}_{\beta}}{\partial n_{\mathcal{K}_{2,\beta}}} = \sum_{\beta=1}^{2} \left\langle \mathbb{A}^{2,\beta} \boldsymbol{\nabla} \boldsymbol{w}_{\beta}, \boldsymbol{n} \right\rangle - \left\langle \boldsymbol{b}^{2,\beta} \boldsymbol{u}_{\beta}, \boldsymbol{n} \right\rangle$$

$$= \left\langle \mathbb{I} \boldsymbol{\nabla} \boldsymbol{w}_{2}, \boldsymbol{n} \right\rangle = \left\langle \boldsymbol{\nabla} v, \boldsymbol{n} \right\rangle$$

$$= \frac{\partial v}{\partial \boldsymbol{n}} \tag{2.11}$$

Б

So with \mathcal{K} operator one can impose the following boundary conditions

~

$$\boldsymbol{w}_{\alpha} = g_{\alpha}^{D} \qquad \qquad \text{on } \Gamma_{\alpha}^{D}, \; \forall \alpha \in [\![1,2]\!],$$
$$\frac{\partial \boldsymbol{w}}{\partial n_{\mathcal{K}_{\alpha}}} + a_{\alpha}^{R} \boldsymbol{w}_{\alpha} = g_{\alpha}^{R} \qquad \qquad \text{on } \Gamma_{\alpha}^{R}, \; \forall \alpha \in [\![1,2]\!]$$

i.e.

$$\begin{aligned} u &= g_1^D & \text{on } \Gamma_1^D, & v &= g_2^D & \text{on } \Gamma_2^D, \\ \frac{\partial u}{\partial \boldsymbol{n}} &+ a_1^R u &= g_1^R & \text{on } \Gamma_1^R, & \frac{\partial v}{\partial \boldsymbol{n}} &+ a_2^R v &= g_2^R & \text{on } \Gamma_2^R \end{aligned}$$

Remark 2.1 One can neither impose *clamped plate* (2.2) nor *Pure Hinged Plate* (2.4) boundary conditions with \mathcal{K} operator. This is why thereafter we will only use the \mathcal{G} operator.

In the same way, with the operator \mathcal{G} given in (2.8), the components of the conormal derivative of \boldsymbol{w} defined in (1.17) are given by

$$\frac{\partial \boldsymbol{w}}{\partial n_{\mathcal{G}_{1}}} \stackrel{\text{def}}{=} \sum_{\beta=1}^{2} \frac{\partial \boldsymbol{w}_{\beta}}{\partial n_{\mathcal{G}_{1,\beta}}} = \sum_{\beta=1}^{2} \left\langle \mathbb{A}^{1,\beta} \boldsymbol{\nabla} \boldsymbol{w}_{\beta}, \boldsymbol{n} \right\rangle - \left\langle \boldsymbol{b}^{1,\beta} \boldsymbol{u}_{\beta}, \boldsymbol{n} \right\rangle$$

$$= \left\langle \mathbb{I} \boldsymbol{\nabla} \boldsymbol{w}_{2}, \boldsymbol{n} \right\rangle = \left\langle \boldsymbol{\nabla} v, \boldsymbol{n} \right\rangle$$

$$= \frac{\partial v}{\partial \boldsymbol{n}}$$
(2.12)

 and

$$\frac{\partial \boldsymbol{w}}{\partial n_{\mathcal{G}_2}} \stackrel{\text{def}}{=} \sum_{\beta=1}^2 \frac{\partial \boldsymbol{w}_\beta}{\partial n_{\mathcal{G}_{2,\beta}}} = \sum_{\beta=1}^2 \left\langle \mathbb{A}^{2,\beta} \, \boldsymbol{\nabla} \, \boldsymbol{w}_\beta, \boldsymbol{n} \right\rangle - \left\langle \boldsymbol{b}^{2,\beta} \boldsymbol{u}_\beta, \boldsymbol{n} \right\rangle \\
= \left\langle \mathbb{I} \, \boldsymbol{\nabla} \, \boldsymbol{w}_1, \boldsymbol{n} \right\rangle = \left\langle \boldsymbol{\nabla} \, \boldsymbol{u}, \boldsymbol{n} \right\rangle \\
= \frac{\partial u}{\partial \boldsymbol{n}}$$
(2.13)

Let us denotes the two partitions avec the boundary Γ :

 $\mathring{\Gamma}^{D}_{\alpha} \cap \mathring{\Gamma}^{R}_{\alpha} = \emptyset \text{ and } \Gamma^{D}_{\alpha} \cup \Gamma^{R}_{\alpha} = \Gamma, \quad \forall \alpha \in [\![1, 2]\!]$ (2.14)

From Vector BVP (1.14)-(1.16), using \mathcal{G} operator one can impose the following boundary conditions

$$\begin{split} \boldsymbol{w}_{\alpha} = g_{\alpha}^{D} & \text{on } \Gamma_{\alpha}^{D}, \; \forall \alpha \in [\![1,2]\!], \\ \frac{\partial \boldsymbol{w}}{\partial n_{\mathcal{G}_{\alpha}}} + a_{\alpha}^{R} \boldsymbol{w}_{\alpha} = g_{\alpha}^{R} & \text{on } \Gamma_{\alpha}^{R}, \; \forall \alpha \in [\![1,2]\!] \end{split}$$

i.e.

$$\begin{aligned} u &= g_1^D & \text{on } \Gamma_1^D, & v &= g_2^D & \text{on } \Gamma_2^D, \\ \frac{\partial v}{\partial \boldsymbol{n}} &+ a_1^R u &= g_1^R & \text{on } \Gamma_1^R, & \frac{\partial u}{\partial \boldsymbol{n}} &+ a_2^R v &= g_2^R & \text{on } \Gamma_2^R \end{aligned}$$

To resume, we give a generic biharmonic BVP using the operator \mathcal{G} in *Vector* BVP (3) which is equivalent to the generic mixed formulation for the biharmonic BVP given in *Vector* BVP (4)

Vector BVP 3 : generic biharmonic BVP with
$$\mathcal{G}$$
 operator
Find $\boldsymbol{w} = (\boldsymbol{w}_1, \boldsymbol{w}_2) \in (\mathrm{H}^2(\Omega))^2$ such that
 $\mathcal{G}(\boldsymbol{w}) = \begin{pmatrix} f \\ 0 \end{pmatrix}$ in Ω , (2.15)
 $\boldsymbol{w}_1 = g_1^D$ on Γ_1^D , $\boldsymbol{w}_2 = g_2^D$ on Γ_2^D , (2.16)
 $\frac{\partial \boldsymbol{w}}{\partial n_{\mathcal{G}_1}} + a_1^R \boldsymbol{w}_1 = g_1^R$ on Γ_1^R , $\frac{\partial \boldsymbol{w}}{\partial n_{\mathcal{G}_2}} + a_2^R \boldsymbol{w}_2 = g_2^R$ on Γ_2^R . (2.17)

Vector BVP 4 : generic mixed formulation for the biharmonic BVP Find $\boldsymbol{w} = (u, v) \in (\mathrm{H}^2(\Omega))^2$ such that

$$\begin{pmatrix} 0 & \mathcal{L}_{\mathbb{I},\mathbf{0},\mathbf{0},0} \\ \mathcal{L}_{\mathbb{I},\mathbf{0},\mathbf{0},0} & \mathcal{L}_{\mathbb{O},\mathbf{0},\mathbf{0},-1} \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix} = \begin{pmatrix} f \\ 0 \end{pmatrix} \qquad \text{in } \Omega, \qquad (2.18)$$

$$\frac{\partial v}{\partial \boldsymbol{n}} + a_1^R u = g_1^R \qquad \text{on } \Gamma_1^R, \qquad \frac{\partial u}{\partial \boldsymbol{n}} + a_2^R v = g_2^R \qquad \text{on } \Gamma_2^R. \tag{2.19}$$

It's very easy to write (2.15) (or (2.18)) from the generic formulation of the biharmonic BVP with \mathcal{G} operator with the FC-VFEMP₁ package: the source code is given in Listing 2.4 where Th is a given siMesh object and f a given python function or scalar.

from fc_vfemp1.operators import Loperator, Hoperator from fc_vfemp1.BVP import BVP,PDE Lop=Loperator (dim=2,A=[[1,None],[None,1]]) Gop=Hoperator (dim=2,m=2) Gop.H[0][1]=Gop.H[1][0]=Lop Gop.H[1][1]=Loperator (dim=2,a0=-1) pde=PDE(Op=Gop, f=[f,0])bvp=BVP(Th, pde=pde)

Listing 2.3: Writing the $\mathcal{G}(\boldsymbol{w}) = \begin{pmatrix} f \\ 0 \end{pmatrix}$ with the FC-VFEMP₁ package

or more concisely FC-VFEM $\mathbb{P}_1\text{-}BIHARMONIC$ package:

import fc_vfemp1_biharmonic.lib as blib bvp=blib.BiharmonicBVP(Th, f=f) Listing 2.4: Writing shortly the $\mathcal{G}(\boldsymbol{w}) = (f, 0)^t$ with the FC-VFEMP₁-BIHARMONIC package

Remark 2.2 By default the boundary conditions of a BVP object are set to homogeneous Neumann so we have

$$\frac{\partial \boldsymbol{w}}{\partial n_{\mathcal{G}_1}} = \frac{\partial \boldsymbol{w}}{\partial n_{\mathcal{G}_2}} = 0 \quad \Leftrightarrow \quad \frac{\partial v}{\partial \boldsymbol{n}} = \frac{\partial u}{\partial \boldsymbol{n}} = 0$$

which is the homogeneous Cahn-Hilliard boundary condition.

Now we will see in the next sections how to set the **Clamped Plate** (CP), **Simply Supported Plate** (CP) and **Cahn-Hilliard** (CH) boundary conditions.

2.2 Some boundary conditions

Let $\Gamma_{lab} \subset \Gamma$. We want to set one of the following boundary conditions on Γ_{lab} :

• Clamped Plate (CP) or pure Dirichlet type:

$$u = g_a \text{ and } \frac{\partial u}{\partial \boldsymbol{n}} = g_b \text{ on } \Gamma_{\text{lab}}$$
 (2.21)

• Simply Supported Plate (SSP) or Navier type :

$$u = g_a \text{ and } \Delta u = -g_b \text{ on } \Gamma_{\text{lab}}$$
 (2.22)

• Cahn-Hilliard (CH) type

$$\frac{\partial u}{\partial n} = g_a \text{ and } \frac{\partial \Delta u}{\partial n} = -g_b \text{ on } \Gamma_{\text{lab}}$$
 (2.23)

Now we will see how to rewrite theses boundary conditions as those in *Vector* BVP 4, equations (2.19)-(2.20), and *Vector* BVP 3, equations (2.16)-(2.17).

2.2.1 Clamped Plate boundary condition

From (2.19) and (2.20), we deduce that (2.21) imposes

$$u = g_a \text{ on } \Gamma_{\text{lab}} \subset \Gamma_1^D \text{ and } \frac{\partial u}{\partial \boldsymbol{n}} = g_b \text{ on } \Gamma_{\text{lab}} \subset \Gamma_2^R$$

So with \mathcal{G} operator and with $\boldsymbol{w} = (u, v)$ we obtain

$$w_1 = g_a \text{ on } \Gamma_{\text{lab}} \subset \Gamma_1^D \text{ and } \frac{\partial \boldsymbol{w}}{\partial n_{\mathcal{G}_2}} = g_b \text{ on } \Gamma_{\text{lab}} \subset \Gamma_2^R$$

Let by be the BVP object build in Listing 2.4. We want to set this object with the (CP) boundary condition. To set the dirichlet condition on first component $w_1 = g_a$ on Γ_{lab} , we can use the setDirichlet method of the BVP object:

bvp.setDirichlet(lab,ga,comps=[0])

As python uses 0-based indexing, the first component is selected with comps=[0]. To set the Neumann condition on second component $\frac{\partial w}{\partial ng_2} = g_b$ we can use the setRobin method of the BVP object: bvp.setRobin(lab,gb,comps=[1])

As python uses 0-based indexing, the second component is selected with comps=[1].

A more convenient way is to use the dedicated function setClampedPlate function:

import fc_vfemp1_biharmonic.lib as blib blib.setClampedPlate(bvp,lab,[ga,gb]) Listing 2.5: Setting a (CP) boundary condition

2.2.2 Simply Supported Plate boundary condition

From (2.19) and (2.20), we deduce that (2.22) imposes

 $u = g_a$ on $\Gamma_{\text{lab}} \subset \Gamma_1^D$ and $v = g_b$ on $\Gamma_{\text{lab}} \subset \Gamma_2^D$

So with \mathcal{G} operator and with $\boldsymbol{w} = (u, v)$ we obtain

 $w_1 = g_a \text{ on } \Gamma_{\text{lab}} \subset \Gamma_1^D \text{ and } w_2 = g_b \text{ on } \Gamma_{\text{lab}} \subset \Gamma_2^D$

Let by be the BVP object build in Listing 2.4. We want to set this object with the (SSP) boundary condition. To set the dirichlet conditions, we can use the setDirichlet method of the BVP object:

bvp.setDirichlet(lab,ga,comps=[0])
bvp.setDirichlet(lab,gb,comps=[1])

or

bvp. setDirichlet (lab,[ga,gb])

A more convenient way is to use the dedicated function setSimplySupportedPlate function:

import fc_vfemp1_biharmonic.lib as blib blib.setSimplySupportedPlate(bvp,lab,[ga,gb]) Listing 2.6: Setting a (SSP) boundary condition

2.2.3 Cahn-Hilliard boundary condition

From (2.19) and (2.20), we deduce that (2.23) imposes

$$\frac{\partial v}{\partial n} = g_b \text{ on } \Gamma_{\text{lab}} \subset \Gamma_1^R \text{ and } \frac{\partial u}{\partial \boldsymbol{n}} = g_a \text{ on } \Gamma_{\text{lab}} \subset \Gamma_2^R$$

where $v = -\Delta u$.

So with \mathcal{G} operator and with $\boldsymbol{w} = (u, v)$ we obtain

$$\frac{\partial \boldsymbol{w}}{\partial n_{\mathcal{G}_1}} = g_b \text{ on } \Gamma_{\text{lab}} \subset \Gamma_1^R \text{ and } \frac{\partial \boldsymbol{w}}{\partial n_{\mathcal{G}_2}} = g_a \text{ on } \Gamma_{\text{lab}} \subset \Gamma_2^R$$

Let by be the BVP object build in Listing 2.4. We want to set this object with the (CH) boundary condition. To set the Neumann conditions, we can use the setRobin method of the BVP object:

bvp.setRobin(lab,gb,comps=[0])bvp.setRobin(lab,ga,comps=[1])

or more concisely

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bvp.setRobin(lab,[gb,ga])

A more convenient way is to use the dedicated function setCahnHilliard function:

import fc_vfemp1_biharmonic.lib as blib blib.setCahnHilliard(bvp,lab,[ga,gb]) Listing 2.7: Setting a (CH) boundary condition

2.3 Examples with exact solutions

To obtain biharmonic problems with exact solutions we give use the exact solution and using **sympy** package we compute the functions $v = -\Delta u_{\text{ex}}$, $f = -\Delta v$, $\frac{\partial u_{\text{ex}}}{\partial x}$, $\frac{\partial u_{\text{ex}}}{\partial y}$, $\frac{\partial v}{\partial x}$ and $\frac{\partial v}{\partial y}$.

Then on simple geometry (square, disk, ...) the RHS terms in the boundary conditions (i.e. g_a or g_b) can be analytically computed since the exterior normals are very simple.

Usual BVP 2 : Biharmonic problem with clamped plate (CP) boundary conditions Find u such that

 $\Delta^2 u = f, \qquad \text{in } \Omega \subset \mathbb{R}^2$ $u = g_a \quad \text{and} \quad \frac{\partial u}{\partial n} = g_b \quad \text{on } \Gamma$

Usual BVP 3 : Biharmonic problem with simply supported plate (SSP) boundary conditions Find u such that

 $\begin{array}{ll} \Delta^2 u = f, & \text{in } \Omega \subset \mathbb{R}^2 \\ u = g_a \quad \text{and} \quad \Delta u = g_b & \text{on } \Gamma \end{array}$

Usual BVP 4 : Biharmonic problem with Cahn-Hilliard (CH) boundary conditions Find u such that

 $\begin{array}{ll} \Delta^2 u = f, & \text{in } \Omega \subset \mathbb{R}^2\\ \frac{\partial u}{\partial n} = g_a \quad \text{and} \quad \frac{\partial \Delta u}{\partial n} = g_b & \text{on } \Gamma \end{array}$

2.3.1

Clamped plate problems on the unit square

The mesh of the unit square $[0,1] \times [0,1]$ can be obtained by using the HyperCube function of the FC-SIMESH package and we obtain a regular mesh. An other way is to generate a mesh file by using gmsh and a given *.geo* file. This can be done entirely by using FC-OOGMSH and FC-SIMESH packages, and the *square4.geo* file. The complete codes are given in Listing 3 and 10 with graphical representation of the obtained meshes. One can see that the label of the boundaries are the same on both meshes.



In file biharmonic_CP_square_ex.py¹) the run function can solve the clamped plate problem, Usual BVP 2, on the unit square for a given exact solution u_{ex} as a string (default is $\sin(x) \cdot \sin(y)$). Now we will set the elemped plate boundary conditions on this problem. On each boundary we can

Now we will set the clamped plate boundary conditions on this problem. On each boundary we can compute $g_a = u_{\text{ex}}$ and $g_b = \frac{\partial u_{\text{ex}}}{\partial n} \stackrel{\text{def}}{=} \langle \nabla u_{\text{ex}}, \boldsymbol{n} \rangle$ where \boldsymbol{n} is the exterior normal to Γ :

$$g_b = \frac{\partial u_{\text{ex}}}{\partial n} = \left\langle \nabla u_{\text{ex}}, \begin{pmatrix} -1\\0 \end{pmatrix} \right\rangle = -\frac{\partial u_{\text{ex}}}{\partial x} \qquad \text{on } \Gamma_1$$

$$g_b = \frac{\partial u_{\text{ex}}}{\partial n} = \left\langle \nabla u_{\text{ex}}, \begin{pmatrix} 1\\0 \end{pmatrix} \right\rangle = \frac{\partial u_{\text{ex}}}{\partial x} \qquad \text{on } \Gamma_2$$

$$g_b = \frac{\partial u_{\text{ex}}}{\partial n} = \left\langle \nabla u_{\text{ex}}, \begin{pmatrix} 0\\-1 \end{pmatrix} \right\rangle = -\frac{\partial u_{\text{ex}}}{\partial y} \qquad \text{on } \Gamma_3$$
$$\frac{\partial u_{\text{ex}}}{\partial y} = \left\langle \begin{pmatrix} 0\\-1 \end{pmatrix} \right\rangle = \frac{\partial u_{\text{ex}}}{\partial y}$$

$$g_b = \frac{\partial u_{\text{ex}}}{\partial n} = \left\langle \nabla u_{\text{ex}}, \begin{pmatrix} 0\\1 \end{pmatrix} \right\rangle = \frac{\partial u_{\text{ex}}}{\partial y} \qquad \text{on } \Gamma_4$$

Part of the source code which sets the biharmonic problem with the 4 boundary conditions is given in Listing 2.10

```
print('***_Setting_the_BVP')
bvp=blib.BiharmonicBVP(Th, f=f)
blib.setClampedPlate(bvp,1,[uex,lambda x,y: -dudx(x,y)])
blib.setClampedPlate(bvp,2,[uex,lambda x,y: dudx(x,y)])
blib.setClampedPlate(bvp,3,[uex,lambda x,y: -dudy(x,y)])
blib.setClampedPlate(bvp,4,[uex,lambda x,y: dudy(x,y)])
```

Listing 2.10: Biharmonic BVP with Clamped Plate (CP) boundary conditions

In Listing 2.11, we solve the clamped plate problem with exact solution $u_{ex} = \sin(5x+1)\cos(3y^2-1)$ and the output is presented. The graphical results are given in Figure 2.1

¹directory fc_vfemp1_biharmonic/examples/





Figure 2.1: 2D biharmonic BVP with CP boundary conditions, u numerical solution (upper left) with error (upper right) and $v = -\Delta u$ numerical solution (bottom left) with error (bottom right)

One can also compute the orders of convergence by using the order function. We use this function in Listing 2.12 and Listing 2.13 on respectively the meshes generated with the HyperCube function and the meshes given by gmsh with square4.geo file. Superconvergence phenomenon with the HyperCube mesh is illustred in Figure 2.2.

e-02
3e-02
9e-02
6e-03
3

Listing 2.13: Computing orders for the biharmonic clamped plate problem with sol='sin(5*x+1)*cos(3*y**2-1)' from fc_vfemp1_biharmonic.examples.biharmonic_CP_square_ex import order order(regular=False, sol='sin(5*x+1)*cos(3*y**2-1)') Output

	Outpu	t	
Solving biharmonic Boundary Value	Problems (RVP's) with		
fc_vfemp1_biharmonic pac			
Copyright (C) 2017 Cuvelier F.	0		
(LAGA/CNRS/Paris 13 University)			
2D biharmonic BVP on [0,1]x	0,1]		
Mesh generated with gmsh and	square4.geo file.		
Laplacian(laplacian	u)) = f		
with boundary conditions			
* Clamped Plate (CP)			
u=ga and du/dn=gb on [1,2,3	, 4]		
1	•		
u=ga and du/dn=gb on [1,2,3 Exact solution : sin(5*x+1)*cos(•		
u=ga and du/dn=gb on [1,2,3 Exact solution : sin(5*x+1)*cos([1/4] N=25	*y**2-1)		
u=ga and du/dn=gb on [1,2,3 Exact solution : sin(5*x+1)*cos([1/4] N=25 Mesh sizes : nq= 891, nme= 16	*y**2-1) 0, h=5.510e-02	2=7.43e-02	
u=ga and du/dn=gb on [1,2,3 Exact solution : sin(5*x+1)*cos([1/4] N=25 Mesh sizes : nq= 891, nme= 16	*y**2-1)	2=7.43e-02	
u=ga and du/dn=gb on [1,2,3 Exact solution : sin(5*x+1)*cos([1/ 4] N=25 Mesh sizes : nq= 891, nme= 16 ndof=1782 - Error : uH1=8.54e-	*y**2-1) 0, h=5.510e-02 3, uL2=1.35e-03, vH1=5.18e-01, vI	2=7.43e-02	
u=ga and du/dn=gb on [1,2,3 Exact solution : sin(5*x+1)*cos(*y**2-1) 0, h=5.510e-02 3, uL2=1.35e-03, vH1=5.18e-01, vI		
u=ga and du/dn=gb on [1,2,3 Exact solution : sin(5*x+1)*cos(*y**2-1) 0, h=5.510e-02 3, uL2=1.35e-03, vH1=5.18e-01, vI 0, h=2.947e-02		
u=ga and du/dn=gb on [1,2,3 Exact solution : sin(5*x+1)*cos([1/4] N=25 Mesh sizes : nq= 891, nme= 160 ndof=1782 - Error : uH1=8.54e- [2/4] N=50 Mesh sizes : nq= 3436, nme= 66 ndof=6872 - Error : uH1=3.86e-	<pre>*y**2-1) 0, h=5.510e-02 3, uL2=1.35e-03, vH1=5.18e-01, vI 0, h=2.947e-02 3, uL2=3.39e-04, vH1=5.13e-01, vI</pre>		
u=ga and du/dn=gb on [1,2,3 Exact solution : sin(5*x+1)*cos([1/4] N=25 Mesh sizes : nq= 891, nme= 16 ndof=1782 - Error : uH1=8.54e- 2/4] N=50 Mesh sizes : nq= 3436, nme= 66 ndof=6872 - Error : uH1=3.86e- 3/4] N=100 Mesh sizes : nq= 13469, nme= 2	<pre>*y**2-1) 0, h=5.510e-02 3, uL2=1.35e-03, vH1=5.18e-01, vI 0, h=2.947e-02 3, uL2=3.39e-04, vH1=5.13e-01, vI</pre>	2=3.30e-02	
<pre>u=ga and du/dn=gb on [1,2,3 Exact solution : sin(5*x+1)*cos(</pre>	<pre>*y**2-1) 0, h=5.510e-02 3, uL2=1.35e-03, vH1=5.18e-01, vI 0, h=2.947e-02 3, uL2=3.39e-04, vH1=5.13e-01, vI 536, h=1.503e-02 03, uL2=8.90e-05, vH1=7.60e-01, v</pre>	2=3.30e-02	
u=ga and du/dn=gb on [1,2,3 Exact solution : sin(5*x+1)*cos(Mesh sizes : nq= 891, nm== 16 ndof=1782 - Error : uH1=8.54e- 2/4] N=50 Mesh sizes : nq= 3436, nme= 66 ndof=6872 - Error : uH1=3.86e- 3/4] N=100 Mesh sizes : nq= 13469, nm== 2 ndof=26938 - Error : uH1=1.88e [4/4] N=150 Mesh sizes : nq= 30081, nm== 5	<pre>*y**2-1) 0, h=5.510e-02 3, uL2=1.35e-03, vH1=5.18e-01, vI 0, h=2.947e-02 3, uL2=3.39e-04, vH1=5.13e-01, vI 536, h=1.503e-02 03, uL2=8.90e-05, vH1=7.60e-01, v</pre>	2=3.30e-02 L2=2.51e-02	



Figure 2.2: 2D biharmonic BVP with CP boundary conditions, order of convergence of u and $v = -\Delta u$ for HyperCube mesh (left) and square4 mesh (right). Superconvergence phenomenon with the HyperCube mesh.

2.3.2 Clamped plate problems on the unit disk

This example is very similar to the previous one. So for better understanding it is better to read in advance the section 2.3.1.

The mesh of the unit disk can be obtained by using gmsh and a given .geo file. This can be done entirely by using FC-OOGMSH and FC-SIMESH packages, and the *disk4bounds.geo* file. The complete code is given in Listing ?? with a graphical representation of the obtained mesh.



In file biharmonic_CP_disk_ex.py²) the run function can solve a (generic) clamped plate problem, Usual BVP 2, on the unit disk for a given *exact* solution u_{ex} as a string (default is $\sin(x) \cdot \sin(y)$).

 $^{^2} directory fc_vfemp1_biharmonic/examples/$

Now we will set the clamped plate boundary conditions on this problem. On each boundary we can compute $g_a = u_{\text{ex}}$ and $g_b = \frac{\partial u_{\text{ex}}}{\partial n} \stackrel{\text{def}}{=} \langle \nabla u_{\text{ex}}, \boldsymbol{n} \rangle$ where $\boldsymbol{n} = \begin{pmatrix} x \\ y \end{pmatrix}$ is the exterior normal to Γ :

$$g_b = \frac{\partial u_{\text{ex}}}{\partial n} = \left\langle \nabla u_{\text{ex}}, \begin{pmatrix} x \\ y \end{pmatrix} \right\rangle = x \frac{\partial u_{\text{ex}}}{\partial x} + y \frac{\partial u_{\text{ex}}}{\partial y} \qquad \text{on } \Gamma$$

Part of the source code which sets the biharmonic problem with the 4 (CP) boundary conditions is given in Listing 2.15

bvp=blib. Biharmonic BVP (Th, f=f)

 $ga{=}uex; gb{=}lambda \ x, y: \ x{*}dudx(x, y){+}y{*}dudy(x, y)$

for lab in [1,2,3,4]:

blib.setClampedPlate(bvp, lab, [ga, gb])

Listing 2.15: Biharmonic BVP with Clamped Plate (CP) boundary conditions on the unit disk

In Listing 2.16, we solve the clamped plate problem with exact solution $u_{ex} = \sin(5x+1)\cos(3y^2-1)$ and the output is presented. The graphical results are given in Figure 2.3





Figure 2.3: 2D biharmonic BVP with CP boundary conditions on the unit disk, u numerical solution (upper left) with error (upper right) and $v = -\Delta u$ numerical solution (bottom left) with error (bottom right)

One can also compute the orders of convergence by using the order function. We use this function in Listing 2.17 and the order are represented in Figure 2.4.





Figure 2.4: 2D biharmonic BVP with CP boundary conditions on the unit disk, order of convergence of u and $v = -\Delta u$.

2.3.3 Simply supported plate problems on the unit square

The mesh of the unit square $[0,1] \times [0,1]$ can be obtained by using the HyperCube function of the FC-SIMESH package and we obtain a regular mesh. An other way is to generate a mesh file by using gmsh and a given *.geo* file. This can be done entirely by using FC-OOGMSH and FC-SIMESH packages, and the *square4.geo* file. The complete codes are given in Listing 3 and 10 with graphical representation of the obtained meshes. One can see that the label of the boundaries are the same on both meshes.

In file biharmonic_SSP_square_ex.py³) the run function can solve a (generic) clamped plate problem, Usual BVP 2, on the unit square for a given exact solution u_{ex} as a string (default is 'sin(x)*sin(y)').

Now we will set the clamped plate boundary conditions on this problem. On each boundary we can compute $g_a = u_{\text{ex}}$ and $g_b = \frac{\partial u_{\text{ex}}}{\partial n} \stackrel{\text{def}}{=} \langle \nabla u_{\text{ex}}, \boldsymbol{n} \rangle$ where \boldsymbol{n} is the exterior normal to Γ :

$$g_b = \frac{\partial u_{\text{ex}}}{\partial n} = \left\langle \nabla u_{\text{ex}}, \begin{pmatrix} -1\\0 \end{pmatrix} \right\rangle = -\frac{\partial u_{\text{ex}}}{\partial x} \qquad \text{on } \Gamma_1$$

$$g_b = \frac{\partial u_{\text{ex}}}{\partial n} = \left\langle \nabla u_{\text{ex}}, \begin{pmatrix} 1\\0 \end{pmatrix} \right\rangle = \frac{\partial u_{\text{ex}}}{\partial x} \qquad \text{on } \Gamma_2$$

$$g_b = \frac{\partial u_{\text{ex}}}{\partial n} = \left\langle \nabla u_{\text{ex}}, \begin{pmatrix} 0 \\ -1 \end{pmatrix} \right\rangle = -\frac{\partial u_{\text{ex}}}{\partial y} \qquad \text{on } \Gamma_3$$

$$g_b = \frac{\partial u_{\text{ex}}}{\partial n} = \left\langle \boldsymbol{\nabla} u_{\text{ex}}, \begin{pmatrix} 0\\1 \end{pmatrix} \right\rangle = \frac{\partial u_{\text{ex}}}{\partial y} \qquad \text{on } \Gamma_4$$

Part of the source code which sets the biharmonic problem with the 4 (SSP) boundary conditions is given in Listing 2.18

bvp=blib.BiharmonicBVP(Th, f=f) for lab in [1,2,3,4]:

blib.setSimplySupportedPlate(bvp, lab, [u, v])

Listing 2.18: Biharmonic BVP with Simply supported plate (SSP) boundary conditions

In Listing 2.19, we solve the clamped plate problem with exact solution $u_{\text{ex}} = \sin(5x+1)\cos(3y^2-1)$ and the output is presented. The graphical results are given in Figure 2.5

³directory fc_vfemp1_biharmonic/examples/





Figure 2.5: 2D biharmonic BVP with SSP boundary conditions, u numerical solution (upper left) with error (upper right) and $v = -\Delta u$ numerical solution (bottom left) with error (bottom right)

One can also compute the orders of convergence by using the order function. We use this function in Listing 2.20 and Listing 2.21 on respectively the meshes generated with the HyperCube function and the meshes given by gmsh with square4.geo file. Superconvergence phenomenon with the HyperCube

mesh is illustred in Figure 2.6.

Listing 2.20: Computing orders f sol = sin(5*x+1)*cos(3*y**2-1)	- the onemonie p	issie with	Simply	sapported	prace	Soundary	contentions	and	** 1 0 11
from fc_vfemp1_biharmonic.examp order(sol='sin(5*x+1)*cos(3*y**		_square_ex	import	order					
		Output							
Solving biharmonic Boundary Value Pro fc_vfemp1_biharmonic package Copyright (C) 2017 Cuvelier F. (LAGA/CURS/Paris 13 University)	blems (BVP's) with								
2D biharmonic BVP on [0,1]x[0,1]									
Mesh generated with HyperCube f									
Laplacian(laplacian(u))	= f								
<pre>with boundary conditions * Simply Supported Plate (SSP) u=gc and Laplacian(u)=gd on [1 Exact solution : sin(5*x+1)*cos(3*y*</pre>									
[1/ 4] N=25									
Mesh sizes : nq= 676, nme= 1250, ndof=1352 - Error : uH1=9.95e-03, [2/ 4] N=50		1e-03, vL2=7	.07e-03						
<pre>Mesh sizes : nq= 2601, nme= 5000, ndof=5202 - Error : uH1=2.51e-03, [3/ 4] N=100</pre>		8e-03, vL2=1	.79e-03						
Mesh sizes : nq= 10201, nme= 20000 ndof=20402 - Error : uH1=6.24e-04,		90e-04, vL2=	4.48e-04						
<pre>[4/ 4] N=150 Mesh sizes : nq= 22801, nme= 45000 ndof=45602 - Error : uH1=2.76e-04,</pre>									

 $\label{eq:listing 2.21: Computing orders for the biharmonic clamped plate problem with $$ sol='sin(5*x+1)*cos(3*y**2-1)' $$ orders for the biharmonic clamped plate problem with $$ sol='sin(5*x+1)*cos(3*y**2-1)' $$ orders for the biharmonic clamped plate problem with $$ sol='sin(5*x+1)*cos(3*y**2-1)' $$ orders for the biharmonic clamped plate problem with $$ sol='sin(5*x+1)*cos(3*y**2-1)' $$ orders for the biharmonic clamped plate problem with $$ sol='sin(5*x+1)*cos(3*y**2-1)' $$ orders for the biharmonic clamped plate problem with $$ sol='sin(5*x+1)*cos(3*y**2-1)' $$ orders for the biharmonic clamped plate problem with $$ sol='sin(5*x+1)*cos(3*y**2-1)' $$ orders for the biharmonic clamped plate problem with $$ sol='sin(5*x+1)*cos(3*y**2-1)' $$ orders for the biharmonic clamped plate problem with $$ sol='sin(5*x+1)*cos(3*y**2-1)' $$ orders for the biharmonic clamped plate problem with $$ sol='sin(5*x+1)*cos(3*y**2-1)' $$ orders for the biharmonic clamped plate problem with $$ sol='sin(5*x+1)*cos(3*y**2-1)' $$ orders for the biharmonic clamped plate problem with $$ sol='sin(5*x+1)*cos(3*y**2-1)' $$ orders for the biharmonic clamped plate problem with $$ sol='sin(5*x+1)*cos(3*y**2-1)' $$ orders for the biharmonic clamped plate problem with $$ sol='sin(5*x+1)*cos(3*y**2-1)' $$ orders for the biharmonic clamped plate problem with $$ sol='sin(5*x+1)*cos(3*y**2-1)' $$ orders for the biharmonic clamped plate problem with $$ sol='sin(5*x+1)*cos(3*y**2-1)' $$ orders for the biharmonic clamped plate problem with $$ sol='sin(5*x+1)*cos(3*y**2-1)' $$ orders for the biharmonic clamped plate problem with $$ sol='sin(5*x+1)*cos(3*y**2-1)' $$ orders for the biharmonic clamped plate problem with $$ sol='sin(5*x+1)*cos(3*y**2-1)' $$ orders for the biharmonic clamped plate problem with $$ sol='sin(5*x+1)*cos(3*y**2-1)' $$ orders for the biharmonic clamped plate problem with $$ sol='sin(5*x+1)*cos(3*y**2-1)' $$ orders for the biharmonic clamped plate p$

 $\begin{array}{ll} \mbox{from } fc_vfemp1_biharmonic.examples.biharmonic_SSP_square_ex \mbox{ import } order \\ order (regular=False, sol='sin(5*x+1)*cos(3*y**2-1)') \end{array}$

	Output	
Solving biharmonic Boundary Value Problems (BVP's) with fc_vfemp1_biharmonic package Copyright (C) 2017 Cuvelier F. (LAGA/CNRS/Paris 13 University)		
2D biharmonic BVP on [0,1]x[0,1] Mesh generated with gmsh and square4.geo file.		
Laplacian(laplacian(u)) = f		
<pre>with boundary conditions * Simply Supported Plate (SSP) u=gc and Laplacian(u)=gd on [1,2,3,4] Exact solution : sin(5*x+1)*cos(3*y**2-1)</pre>		
[1/ 4] N=25 Mesh sizes : nq= 891, nme= 1680, h=5.510e-02		
ndof=1782 - Error : uH1=9.77e-03, uL2=2.01e-03, vH1=1. [2/ 4] N=50	25e-02, vL2=3.59e-03	
Mesh sizes : nq= 3436, nme= 6670, h=2.947e-02 ndof=6872 - Error : uH1=4.21e-03, uL2=5.28e-04, vH1=5.	90e-03, vL2=9.08e-04	
[3/4] N=100 Mesh sizes : ng= 13469, nme= 26536, h=1.503e-02		
ndof=26938 - Error : uH1=1.99e-03, uL2=1.30e-04, vH1=2	2.80e-03, vL2=2.27e-04	
Mesh sizes : nq= 30081, nme= 59560, h=9.872e-03		
ndof=60162 - Error : uH1=1.30e-03, uL2=5.86e-05, vH1=1	.89e-03. vL2=1.03e-04	



Figure 2.6: 2D biharmonic BVP with (SSP) boundary conditions, order of convergence of u and $v = -\Delta u$ for HyperCube mesh (left) and square4 mesh (right). Superconvergence phenomenon with the HyperCube mesh.

2.3.4 Simply supported plate problems on the unit disk

For better understanding it is better to read in advance the section 2.3.1.

The mesh of the unit disk can be obtained by using gmsh and a given .geo file. This can be done entirely by using FC-OOGMSH and FC-SIMESH packages, and the *disk4bounds.geo* file. The complete code is given in Listing ?? with a graphical representation of the obtained mesh.

In file biharmonic_SSP_disk_ex.py⁴) the run function can solve a (generic) simply supported plate problem, Usual BVP 3, on the unit disk for a given exact solution u_{ex} as a string (default is $'\sin(x)*\sin(y)'$).

Now we will set the simply supported plate boundary conditions on this problem. On each boundary we can compute $g_a = u_{\text{ex}}$ and $g_b = -v$.

Part of the source code which sets the biharmonic problem with the 4 boundary conditions is given in Listing 2.22

bvp=blib.BiharmonicBVP(Th, f=f)

for lab in [1,2,3,4]:

blib.setSimplySupportedPlate(bvp, lab, [u, v])

Listing 2.22: Biharmonic BVP with Simply Supported Plate (SSP) boundary conditions on the unit disk

In Listing 2.23, we solve the simply supported plate problem with exact solution $u_{\text{ex}} = \sin(5x + 1)\cos(3y^2 - 1)$ and the output is presented. The graphical results are given in Figure 2.7

⁴directory fc_vfemp1_biharmonic/examples/





Figure 2.7: Biharmonic BVP with SSP boundary conditions on the unit disk, u numerical solution (upper left) with error (upper right) and $v = -\Delta u$ numerical solution (bottom left) with error (bottom right)

One can also compute the orders of convergence by using the order function. We use this function in Listing 2.24 and the order are represented in Figure 2.8.

	$ \begin{array}{l} \mathbf{m} \ \ \mathbf{fc_vfemp1_biharmonic.examples.biharmonic_SSP_disk_ex \ \mathbf{import} \ \ \mathbf{or} \ der \\ \mathrm{der} \ (\ \mathbf{sol}{='} \ \mathbf{sin} \ (5*x+1)*\cos \left(3*y**2{-}1 \right) \ ' \) \end{array} $
	Output
 Sol	Lving biharmonic Boundary Value Problems (BVP's) with
	fc_vfemp1_biharmonic package
Сор	oyright (C) 2017 Cuvelier F.
((LAGA/CNRS/Paris 13 University)
	2D biharmonic BVP on unit disk
	Mesh generated with gmsh and disk4bounds.geo file.
	Laplacian(laplacian(u)) = f
wi	ith boundary conditions
	* Simply Supported Plate (SSP)
	u=gc and Laplacian(u)=gd on [1,2,3,4]
Еx	<pre>cact solution : sin(5*x+1)*cos(3*y**2-1)</pre>
[1	./ 6] N=25
1	Mesh sizes : nq= 2766, nme= 5370, h=5.760e-02
:	ndof=5532 - Error : uH1=1.16e-02, uL2=8.13e-03, vH1=1.18e-02, vL2=3.90e-03
-	2/ 6] N=75
	Mesh sizes : nq= 23549, nme= 46624, h=2.127e-02
	ndof=47098 - Error : uH1=2.93e-03, uL2=9.83e-04, vH1=3.61e-03, vL2=4.63e-04
	3/ 6] N=100
	Mesh sizes : nq= 42319, nme= 84004, h=1.539e-02 ndof=84638 - Error : uH1=2.08e-03, uL2=5.21e-04, vH1=2.62e-03, vL2=2.51e-04
	ndo1-94030 - Effor : uni-2.000-03, ul2-0.210-04, Vni-2.020-03, Vl2-2.510-04 (6) N=150
-	z oj n-150 Mesh sizes : nq= 94571, nme= 188196, h=1.060e-02
	ndof=189142 - Error : uH1=1.37e-03, uL2=2.38e-04, vH1=1.77e-03, vL2=1.13e-04
	/ 6] N=200
	Mesh sizes : ng=167069, nme= 332876, h=7.726e-03
	ndof=334138 - Error : uH1=1.02e-03, uL2=1.35e-04, vH1=1.32e-03, vL2=6.40e-05
	5/ 6] N=250
l	Mesh sizes : nq=261161, nme= 520748, h=6.306e-03
	ndof=522322 - Error : uH1=8.14e-04, uL2=8.48e-05, vH1=1.05e-03, vL2=4.07e-05



Figure 2.8: 2D biharmonic BVP with (SSP) boundary conditions on the unit disk, order of convergence of u and $v = -\Delta u$.

2.4 Examples

2.4.1 Mixed boundary conditions on a disk with 5 holes

The domain Ω and its boundaries generated by gmsh are represented in Figure 2.9.



Figure 2.9: Disk with 5 holes : gmsh mesh

We study the following biharmonic BVP with mixed boundary conditions :



Part of the source code (file fc_vfemp1_biharmonic/examples/biharmonic_Mixed_disk5holes_01.py) is given in Listing 2.25

```
meshfile=gmsh.buildmesh2d(geoFile,N, force=True,verbose=0)
Th=siMesh(meshfile)
bvp=blib.BiharmonicBVP(Th,f=0)
blib.setClampedPlate(bvp,1,[0,0])
blib.setClampedPlate(bvp,10,[0,0])
for lab in [20,21,22,23]:
    blib.setSimplySupportedPlate(bvp,lab,[1,0])
U=bvp.solve(split=True)
```

Listing 2.25: Mixed boundary conditions on a disk with 5 holes

We represent in Figure 2.10 the numerical error for u computation on the gmsh mesh with $n_q = 83324$ and $n_{me} = 165044$.



Figure 2.10: mixed boundary conditions on a disk with 5 holes, (CP) (0,0) on Γ_1 , (CH) (0,0) on Γ_{10} , (SSP) (1,0) on $\Gamma_{20} \cup \Gamma_{21} \cup \Gamma_{22} \cup \Gamma_{23}$. *u* numerical solution (left) and $v = -\Delta u$ numerical solution (right)

We represent in Figure 2.11 the same problem except on Γ_{10} : we set a (CP) boundary condition instead of a (CH) boundary condition:

(CP)
$$u = 0$$
 and $\frac{\partial u}{\partial \boldsymbol{n}} = 0$, on Γ_{10} .

Part of the source code (file biharmonic_Mixed_disk5holes_01.py⁵) is given in Listing 2.26

```
meshfile=gmsh.buildmesh2d(geoFile,N, force=True,verbose=0)
Th=siMesh(meshfile)
bvp=blib.BiharmonicBVP(Th,f=0)
blib.setClampedPlate(bvp,1,[0,0])
blib.setClampedPlate(bvp,10,[0,0])
for lab in [20,21,22,23]:
    blib.setSimplySupportedPlate(bvp,lab,[1,0])
U=bvp.solve(split=True)
```

Listing 2.26: Mixed boundary conditions on a disk with 5 holes

The source code is given in file biharmonic_Mixed_disk5holes_01.py⁶



Figure 2.11: mixed boundary conditions on a disk with 5 holes, (CP) (0,0) on $\Gamma_1 \cup \Gamma_{10}$, (SSP) (1,0) on $\Gamma_{20} \cup \Gamma_{21} \cup \Gamma_{22} \cup \Gamma_{23}$. *u* numerical solution (left) and $v = -\Delta u$ numerical solution (right)

⁵ directory fc_vfemp1_biharmonic/examples/

 $^{^{6}\ {\}rm directory}\ {\tt fc_vfemp1_biharmonic/examples/}$

2.4.2 2D Biharmonic BVP with (CP) and (CH) boundary conditions

This example comes from [6](p.3104). Let $\Omega = [-1, 1] \times [0, 1]$, $\Gamma_A = \{[-1, 0] \times \{y = 0\}\} \cup \{\{x = 1\} \times [0, 1]\}$, and $\Gamma_B = \Gamma \setminus \Gamma_A$. The domain Ω and its boundaries generated by gmsh are represented in Figure 2.12. With this mesh, we have $\Gamma_A = \Gamma_1 \cup \Gamma_3$ and $\Gamma_B = \Gamma_2 \cup \Gamma_4 \cup \Gamma_5$.



Figure 2.12: 2D biharmonic BVP domain : gmsh mesh

We study the biharmonic BVP with mixed boundary conditions, clamped plate (CP) on Γ_A and Cahn-Hilliard (CH) on Γ_B .



Part of the source code (file fc_vfemp1_biharmonic/examples/biharmonic_CP_CH_rectangle01_crack01.py) is given in Listing 2.27

```
meshfile=gmsh.buildmesh2d(geoFile,N, force=True,verbose=0)
Th=siMesh(meshfile)
bvp=blib.BiharmonicBVP(Th,f=0)
blib.setClampedPlate(bvp,1,[0,0])
blib.setClampedPlate(bvp,3,[1,0])
U=bvp.solve(split=True)
```

Listing 2.27: 2D biharmonic BVP with (CP)-(CH) boundary conditions with crack singularities

We represent in Figure 2.13 the numerical error for u computation on the gmsh mesh with $n_q = 59825$ and $n_{me} = 118748$.



Figure 2.13: 2D biharmonic BVP with (CP)-(CH) boundary conditions, u numerical solution (left) and $v = -\Delta u$ numerical solution (right)

Chapter 3

Pseudo-biharmonic Boundary Value Problems

3.1 Clamped grid problem

In [7] page 74, the operator $\frac{\partial^4 u}{\partial x^4} + \frac{\partial^4 u}{\partial y^4}$ is used as a model of an elastic medium consisting in two sets of intertwined (not glued) perpendicular fibers running in Cartesian directions (Figure 3.1). The main assumption here is that those sets of fibers are connected in such a way that the vertical positions coincide but there is no connection that forces a torsion in the fibers.



Figure 3.1: A fragment of an elastic grid.

The Clamped grid problem is

$$\begin{cases} \frac{\partial^4 u}{\partial x^4} + \frac{\partial^4 u}{\partial y^4} &= f \text{ in } \Omega \\ u = \frac{\partial u}{\partial \mathbf{n}} &= 0 \text{ on } \Gamma \end{cases}$$

$$(3.1)$$

We have

$$\frac{\partial^4}{\partial x^4} + \frac{\partial^4}{\partial y^4} = \left(-\Delta - \sqrt{2}\frac{\partial^2}{\partial x \partial y}\right) \left(-\Delta + \sqrt{2}\frac{\partial^2}{\partial x \partial y}\right)$$

and problem (3.1) may be split into :

Find u and v such that $\begin{cases}
-\Delta v - \sqrt{2} \frac{\partial^2 v}{\partial x \partial y} &= f, \text{ in } \Omega \\
-\Delta u + \sqrt{2} \frac{\partial^2 u}{\partial x \partial y} &= v, \text{ in } \Omega \\
u = \frac{\partial u}{\partial n} &= 0, \text{ on } \Gamma
\end{cases}$

The two first equations can be equivalently written as

$$\mathcal{G}\begin{pmatrix} u\\v \end{pmatrix} = \begin{pmatrix} f\\0 \end{pmatrix} \quad \text{or} \quad \mathcal{K}\begin{pmatrix} u\\v \end{pmatrix} = \begin{pmatrix} 0\\f \end{pmatrix}$$
 (3.3)

where ${\mathcal G}$ and ${\mathcal K}$ are the ${\mathcal H}\text{-}{\rm operators}$ defined by

$$\mathcal{G} = \begin{pmatrix} 0 & \mathcal{L}_{\mathbb{E},\mathbf{0},\mathbf{0},0} \\ \mathcal{L}_{\mathbb{F},\mathbf{0},\mathbf{0},0} & \mathcal{L}_{\mathbb{O},\mathbf{0},\mathbf{0},-1} \end{pmatrix} \text{ and } \mathcal{K} = \begin{pmatrix} \mathcal{L}_{\mathbb{F},\mathbf{0},\mathbf{0},0} & \mathcal{L}_{\mathbb{O},\mathbf{0},\mathbf{0},0} \\ \mathcal{L}_{\mathbb{O},\mathbf{0},\mathbf{0},0} & \mathcal{L}_{\mathbb{E},\mathbf{0},\mathbf{0},0} \end{pmatrix}$$
(3.4)

with

$$\mathbb{E} = \begin{pmatrix} 1 & \frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & 1 \end{pmatrix} \quad \text{and} \quad \mathbb{F} = \begin{pmatrix} 1 & -\frac{\sqrt{2}}{2} \\ -\frac{\sqrt{2}}{2} & 1 \end{pmatrix}.$$

We choose these expressions for $\mathbb E$ and $\mathbb F$ to preserve symetry.

Let $\boldsymbol{w} = (u, v)$. From (3.3), the components of the conormal derivative of \boldsymbol{w} defined in (1.17) are given by

$$\frac{\partial \boldsymbol{w}}{\partial n_{\mathcal{K}_{1}}} \stackrel{\text{def}}{=} \sum_{\beta=1}^{2} \frac{\partial \boldsymbol{w}_{\beta}}{\partial n_{\mathcal{K}_{1,\beta}}} = \sum_{\beta=1}^{2} \left\langle \mathbb{A}^{1,\beta} \boldsymbol{\nabla} \boldsymbol{w}_{\beta}, \boldsymbol{n} \right\rangle - \left\langle \boldsymbol{b}^{1,\beta} \boldsymbol{u}_{\beta}, \boldsymbol{n} \right\rangle$$

$$= \left\langle \mathbb{F} \boldsymbol{\nabla} \boldsymbol{w}_{1}, \boldsymbol{n} \right\rangle = \left\langle \mathbb{F} \boldsymbol{\nabla} u, \boldsymbol{n} \right\rangle = \frac{\partial \boldsymbol{w}}{\partial n_{\mathcal{G}_{2}}} \tag{3.5}$$

 and

$$\frac{\partial \boldsymbol{w}}{\partial n_{\mathcal{K}_2}} \stackrel{\text{def}}{=} \sum_{\beta=1}^2 \frac{\partial \boldsymbol{w}_\beta}{\partial n_{\mathcal{K}_{2,\beta}}} = \sum_{\beta=1}^2 \left\langle \mathbb{A}^{2,\beta} \boldsymbol{\nabla} \boldsymbol{w}_\beta, \boldsymbol{n} \right\rangle - \left\langle \boldsymbol{b}^{2,\beta} \boldsymbol{u}_\beta, \boldsymbol{n} \right\rangle$$

$$= \left\langle \mathbb{E} \boldsymbol{\nabla} \boldsymbol{w}_2, \boldsymbol{n} \right\rangle = \left\langle \mathbb{E} \boldsymbol{\nabla} v, \boldsymbol{n} \right\rangle = \frac{\partial \boldsymbol{w}}{\partial n_{\mathcal{G}_1}} \tag{3.6}$$

With \mathcal{G} operator one can impose the following boundary conditions

$$\boldsymbol{w}_{\alpha} = g_{\alpha}^{D} \qquad \text{on } \Gamma_{\alpha}^{D}, \ \forall \alpha \in [\![1,1]\!],$$
$$\frac{\partial \boldsymbol{w}}{\partial n_{\mathcal{G}_{\alpha}}} + a_{\alpha}^{R} \boldsymbol{w}_{\alpha} = g_{\alpha}^{R} \qquad \text{on } \Gamma_{\alpha}^{R}, \ \forall \alpha \in [\![1,2]\!]$$

and we obtain

$$\begin{split} u = & g_1^D & \text{ on } \Gamma_1^D, \text{ and } v = g_2^D & \text{ on } \Gamma_2^D, \\ \left< \mathbb{E} \, \pmb{\nabla} \, v, \pmb{n} \right> + a_1^R u = & g_1^R & \text{ on } \Gamma_1^R, \text{ and } \left< \mathbb{E} \, \pmb{\nabla} \, u, \pmb{n} \right> + a_2^R v = g_2^R & \text{ on } \Gamma_2^R \end{split}$$

(3.2)

To impose clamped grid boundary condition $u = \frac{\partial u}{\partial \mathbf{n}} = 0$ on Γ , we choose $\Gamma_1^D = \Gamma$ (thus $\Gamma_1^R = \emptyset$). As explain in Remark 6.1 of [7], when u = 0 on Γ , the tangential derivatives of u, $\frac{\partial u}{\partial \tau} \stackrel{\text{def}}{=} \nabla u - \langle \nabla u, \mathbf{n} \rangle \mathbf{n}$, is zero on Γ , and then

$$\nabla u = \langle \nabla u, \boldsymbol{n} \rangle \boldsymbol{n}.$$

So we obtain

$$\nabla u, \boldsymbol{n} \rangle = \langle \boldsymbol{\nabla} u, \boldsymbol{n} \rangle \langle \mathbb{F} \boldsymbol{n}, \boldsymbol{n} \rangle = \langle \boldsymbol{\nabla} u, \boldsymbol{n} \rangle (1 - \sqrt{2}n_1 n_2).$$

Since the normal $\boldsymbol{n} = (n_1, n_2) = (\cos \theta, \sin \theta)$ one finds that $n_1 n_2 = \frac{1}{2} \sin(2\theta) \in \left[-\frac{1}{2}, \frac{1}{2}\right]$ and then $1 - \sqrt{2}n_1 n_2 \ge 1 - \frac{\sqrt{2}}{2} > 0.$

Thus, under the asymption u = 0 on Γ , we have on Γ

< (F

$$\frac{\partial u}{\partial \boldsymbol{n}} = 0 \iff \frac{\partial \boldsymbol{w}}{\partial n_{\mathcal{G}_2}} \stackrel{\text{def}}{=} \langle \mathbb{F} \, \boldsymbol{\nabla} \, \boldsymbol{u}, \boldsymbol{n} \rangle = 0$$

<u>and we can write</u>

 $\begin{array}{c} \checkmark \quad \textbf{Vector BVP 5: clamped grid problem (3.2) with \mathcal{G} operator} \\ Find $\boldsymbol{w} = (\boldsymbol{w}_1, \boldsymbol{w}_2) \in (\mathrm{H}^2(\Omega))^2$ such that} \\ & \mathcal{G}(\boldsymbol{w}) = \begin{pmatrix} f \\ 0 \end{pmatrix} & \text{in } \Omega, \\ & \boldsymbol{w}_1 = 0 & \text{on } \Gamma_1^D = \Gamma, \ (\text{so } \Gamma_1^R = \emptyset \) \\ & \frac{\partial \boldsymbol{w}}{\partial n_{\mathcal{G}_2}} = 0 & \text{on } \Gamma_2^R = \Gamma, \ (\text{so } \Gamma_2^D = \emptyset \) \end{array}$

With \mathcal{K} operator one can impose the following boundary conditions

$$\boldsymbol{w}_{\alpha} = g_{\alpha}^{D} \qquad \qquad \text{on } \Gamma_{\alpha}^{D}, \ \forall \alpha \in [\![1,1]\!],$$
$$\frac{\partial \boldsymbol{w}}{\partial n_{\mathcal{K}_{\alpha}}} + a_{\alpha}^{R} \boldsymbol{w}_{\alpha} = g_{\alpha}^{R} \qquad \qquad \text{on } \Gamma_{\alpha}^{R}, \ \forall \alpha \in [\![1,2]\!]$$

and we obtain

$$\begin{split} u = g_1^D & \text{ on } \Gamma_1^D, \text{ and } v = g_2^D & \text{ on } \Gamma_2^D, \\ \langle \mathbb{F} \boldsymbol{\nabla} u, \boldsymbol{n} \rangle + a_1^R u = g_1^R & \text{ on } \Gamma_1^R, \text{ and } \langle \mathbb{E} \boldsymbol{\nabla} v, \boldsymbol{n} \rangle + a_2^R v = g_2^R & \text{ on } \Gamma_2^R. \end{split}$$

If we want to impose clamped grid boundary condition $u = \frac{\partial u}{\partial n} = 0$ on Γ the choice of \mathcal{K} operator is not possible : with u = 0 on $\Gamma_1^D = \Gamma$, we have $\Gamma_1^R = \emptyset$ and we cannot impose $\frac{\partial u}{\partial n} = 0$ on Γ .

3.2 Applications on a rectangular domain

Let Ω_0 be the rectangular domain $[-1, 6] \times [-1, 1]$ and $f_0 := \exp(-100((x + 0.75)^2 + (y - 0.75)^2))$ be the source term as a concentred load. They are represented in Figure 3.6.

We also denote by $\Omega_{\pi/4}$ and $f_{\pi/4}$ respectively the domain Ω and the function f rotated by $\pi/4$ with (0,0) as center. They are represented in Figure 3.7.



Figure 3.2: Domain $\Omega_0 = [-1, 6] \times [-1, 1]$ (left) and function f_0 (right)



Figure 3.3: Domain $\Omega_{\pi/4}$ (left) and function $f_{\pi/4}$ (right)

We study three problems. The first one will be the classical biharmonic clamped plate problem on Ω_0 . The second will be clamped grid problem with the aligned fibers on Ω_0 . The last one will be the clamped grid problem with the diagonal fibers on $\Omega_{\pi/4}$.



As seen in section ?? this problem can be written as a vector boundary value problem and is given in *Vector* BVP ??. Part of the Python code used to solve this problem is given in Listing 3.1

```
print_separator()
print('_____Mesh_sizes_:_nq=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,_nme=%d,
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i\, f \quad v\, er\, b\, o\, s\, e > 0 \colon
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if graphics and isModuleFound('fc simesh matplotlib'):

Listing 3.1: Clamped *plate* problem on $[-1, 6] \times [-1, 1]$

The complete code is given in file $BVP_ClampedPlate_hypermesh_2D01.py$ ¹ and can be run with the following python commands:

3.2.2 Clamped grid problem with the aligned fibers

 $\begin{array}{l}
\overset{\circ}{\sim} Usual \text{ BVP 10}: \text{ Clamped grid problem with the aligned fibers on } \Omega_{0} \\
\text{Find } u \text{ such that} \\
\begin{cases}
\frac{\partial^{4}u}{\partial x^{4}} + \frac{\partial^{4}u}{\partial y^{4}} &= f_{0} \text{ in } \Omega_{0} \\
u = \frac{\partial u}{\partial \mathbf{n}} &= 0 \text{ on } \Gamma = \partial \Omega_{0}
\end{array}$ (3.8)

As seen in section 3.1 this problem can be written as a vector boundary value problem and is given in *Vector* BVP 5. Part of the Python code used to solve this problem is given in Listing 3.2.

 $\begin{array}{ll} f = lambda \ x,y: \ \exp(-100*((x+0.75)**2+(y-0.75)**2)) \\ Th = HyperCube(2,[7*N,2*N], mapping = lambda \ q: \ np.array([-1+7*q[0],2*q[1]-1])) \\ a = 2**(1/2)/2 \\ Hop = Hoperator(dim = 2,m = 2) \\ Hop.H[0][1] = Loperator(dim = 2,A = [[1,a],[a,1]]) \\ Hop.H[1][0] = Loperator(dim = 2,A = [[1,-a],[-a,1]]) \\ Hop.H[1][0] = Loperator(dim = 2,A = [[1,-a],[-a,1]]) \\ Hop.H[1][1] = Loperator(dim = 2,a = -1) \\ pde = PDE(Op = Hop, f = [f, 0]) \\ bvp = BVP(Th, pde = pde) \\ for lab in Th.sThlab[Th.find(d = 1)]: \\ bvp.setDirichlet(lab, 0.0, comps = [0]) \\ U = bvp. solve(split = True) \end{array}$

Listing 3.2: Clamped grid problem on $[-1, 6] \times [-1, 1]$

The complete code is given in file BVP_ClampedAlignedGrid_hypermesh_2D01.py 2 and can be run with the following python commands:

from fc_vfemp1_biharmonic.examples.BVP_ClampedAlignedGrid_hypermesh_2D01 import
 run
 res=run(N=50)

3.2.3 Clamped grid problem with the diagonal fibers

 $\begin{array}{c} & & & \\ &$

The Python code used to solve this problem is very similar to the previous one given in Listing 3.1: we just have to rotate the function f and the domain. These operations are given in Listing 3.3.

 $\begin{array}{l} {\rm theta}{=}{\rm pi}/4 \ \# \ For \ f \ and \ mesh \ rotation \\ {\rm R}{=}[\left[\cos\left({\rm theta}\right), -\sin\left({\rm theta}\right)\right], \left[\sin\left({\rm theta}\right), \cos\left({\rm theta}\right)\right]] \\ {\rm P}{=}{\rm np. \ dot} \left({\rm R}, \left[-0.75, 0.75\right]\right) \\ {\rm f}{=} {\rm lambda} \ {\rm x}, {\rm y}{:} \exp\left(-100{*}\left(\left({\rm x}\ -{\rm P}\left[0\right]\right){*}{*}{2}\ +\ \left({\rm y}\ -{\rm P}\left[1\right]\right){*}{*}{2}\right)\right) \\ {\rm Th}{=} {\rm HyperCube} \left(2, \left[7{*}{\rm N}, 2{*}{\rm N}\right], {\rm mapping}{=} {\rm lambda} \ {\rm q}{:} \\ {\rm np. \ dot} \left({\rm R}, {\rm np. \ array} \left(\left[-1{+}{7}{*}{\rm q}\left[0\right], 2{*}{\rm q}\left[1\right]{-}1\right]\right)\right)\right) \\ {\rm Listing \ 3.3: \ 2D \ clamped \ grid \ BVP \ on \ [-1,6] \times [-1,1] \\ \end{array}$

```
<sup>1</sup>directory fc_vfemp1_biharmonic/examples/
<sup>2</sup>directory fc_vfemp1_biharmonic/examples/
```

The complete code is given in file $BVP_ClampedDiagonalGrid_hypermesh_2D01.py$ ³ and can be run with the following python commands:

from fc_vfemp1_biharmonic.examples.BVP_ClampedDiagonalGrid_hypermesh_2D01 import
 run
res=run(N=50)

3.2.4 Graphical results

For graphical convenience the numerical solutions on the grid with the diagonal fibers are rotated by $-\pi/4$.



Figure 3.4: Displacement u of, respectively, an isotropic rectangular plate (upper left), grid with the aligned fibers (upper right) and grid with the diagonal fibers (bottom).

³directory fc_vfemp1_biharmonic/examples/



Figure 3.5: $v = -\Delta u$ of, respectively, an isotropic rectangular plate (upper left), grid with the aligned fibers (upper right) and grid with the diagonal fibers (bottom).

3.3 Applications on a pentagonal domain

Let Ω_0 be the pentagon

 $\Omega_0 = \{(x,y) \in [-1,2] \times [-1,1] \ : \ y \geqslant -x-1\}$

and $f := \exp(-100((x + 0.75)^2 + (y - 0.75)^2))$ be the source term as a concentred load. They are represented in Figure ??.

We also denote by $\Omega_{\pi/4}$ and $f_{\pi/4}$ respectively the domain Ω and the function f rotated by $\pi/4$ with (0,0) as center. They are represented in Figure ??.



Figure 3.6: Domain Ω_0 (left) and function f_0 (right)



Figure 3.7: Domain $\Omega_{\pi/4}$ (left) and function $f_{\pi/4}$ (right)

We study three problems. The first one will be the classical biharmonic clamped plate problem on Ω_0 . The second will be clamped grid problem with the aligned fibers on Ω_0 . The last one will be the clamped grid problem with the diagonal fibers on $\Omega_{\pi/4}$.

3.3.1 Classical biharmonic Clamped Plate problem

$$\begin{array}{c} \overleftarrow{\Theta}^{-} Usual \text{ BVP 12}: \text{ Clamped plate problem on } \Omega_{0} \\ \hline \\ \text{Find } u \text{ such that} \\ \begin{cases} \Delta^{2}u &= f_{0} \text{ in } \Omega_{0} \\ u = \frac{\partial u}{\partial n} &= 0 \text{ on } \Gamma = \partial \Omega_{0} \end{cases}$$

$$(3.10)$$

As seen in section ?? this problem can be written as a vector boundary value problem and is given in *Vector* BVP ??. Part of the Python code used to solve this problem is given in Listing 3.4.

```
 \begin{array}{ll} f=lambda \ x,y: \ exp(-100*((x+0.75)**2+(y-0.75)**2)) \\ meshfile=gmsh. buildmesh2d(geoFile,N, force=True,verbose=0) \\ Th=siMesh(meshfile) \\ Hop=Hoperator(dim=2,m=2) \\ Hop.H[0][1]=Loperator(dim=2,A=[[1,None],[None,1]]) \\ Hop.H[1][0]=Loperator(dim=2,A=[[1,None],[None,1]]) \\ Hop.H[1][1]=Loperator(dim=2,a0=-1) \\ pde=PDE(Op=Hop,f=[f,0]) \\ bvp=BVP(Th,pde=pde) \\ for lab in Th.sThlab[Th.find(d=1)]: \\ bvp.setDirichlet(lab,0.0,comps=[0]) \\ U=bvp.solve(split=True) \end{array}
```

Listing 3.4: Clamped plate problem on pentagonal domain

The complete code is given in file BVP_ClampedPlate_pentagonal01_2D01.py 4 and can be run with the following python commands:

⁴directory fc_vfemp1_biharmonic/examples/

3.3.2

Clamped grid problem with the aligned fibers

$\begin{array}{c|c} & & & \\$

As seen in section 3.1 this problem can be written as a vector boundary value problem and is given in *Vector* BVP 5. Part of the Python code used to solve this problem is given in Listing 3.5.

$$\begin{split} &f{=}lambda \ x,y: \ exp(-100*((x+0.75)**2+(y-0.75)**2)) \\ &meshfile{=}gmsh. buildmesh2d(geoFile,N, force{=}True, verbose{=}0) \\ &Th{=}siMesh(meshfile) \\ &a{=}2**(1/2)/2 \\ &Hop{=}Hoperator(dim{=}2,m{=}2) \\ &Hop.H[0][1]{=}Loperator(dim{=}2,A{=}[[1,a],[a,1]]) \\ &Hop.H[1][0]{=}Loperator(dim{=}2,A{=}[[1,-a],[-a,1]]) \\ &Hop.H[1][1]{=}Loperator(dim{=}2,a{=}{-}1) \\ &pde{=}PDE(Op{=}Hop, f{=}[f,0]) \\ &bvp{=}BVP(Th, pde{=}pde) \\ &for \ lab \ in \ Th.sThlab[Th.find(d{=}1)]: \\ &bvp.setDirichlet(lab,0.0,comps{=}[0]) \\ &U{=}bvp. \ solve(split{=}True) \end{split}$$



The complete code is given in file BVP_ClampedAlignedGrid_pentagonal01_2D01.py 5 and can be run with the following python commands:

from fc_vfemp1_biharmonic.examples.BVP_ClampedAlignedGrid_pentagonal01_2D01
 import run
 res=run(N=50)

3.3.3 Clamped grid problem with the diagonal fibers

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The Python code used to solve this problem is very similar to the previous one given in Listing 3.4: we just have to rotate the function f and the domain. These operations are given in Listing 3.6

Listing 5.6. 2D clamped grid DV1 ...

The complete code is given in file BVP_ClampedDiagonalGrid_pentagonal01_2D01.py 6 and can be run with the following python commands:

from fc_vfemp1_biharmonic.examples.BVP_ClampedDiagonalGrid_pentagonal01_2D01
 import run
 res=run(N=50)

⁵directory fc_vfemp1_biharmonic/examples/

⁶directory fc_vfemp1_biharmonic/examples/

3.3.4 Graphical results

For graphical convenience the numerical solutions on the grid with the diagonal fibers are rotated by $-\pi/4$.



Figure 3.8: Displacement u of, respectively, an isotropic pentagonal plate (upper left), grid with the aligned fibers (upper right) and grid with the diagonal fibers (bottom).



Figure 3.9: $v = -\Delta u$ of, respectively, an isotropic pentagonal plate (upper left), grid with the aligned fibers (upper right) and grid with the diagonal fibers (bottom).

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 $^{{\}rm GIT: commit} \ 561717c175e5d27bfac7701e0ec81ada934a0d40 \ Date: \ Tue \ Jun \ 13 \ 12:44:39 \ 2017 \ +0200 \ Date: \ Tue \ 13 \$